

Dynamic Capacity Management for Deferred Surgeries

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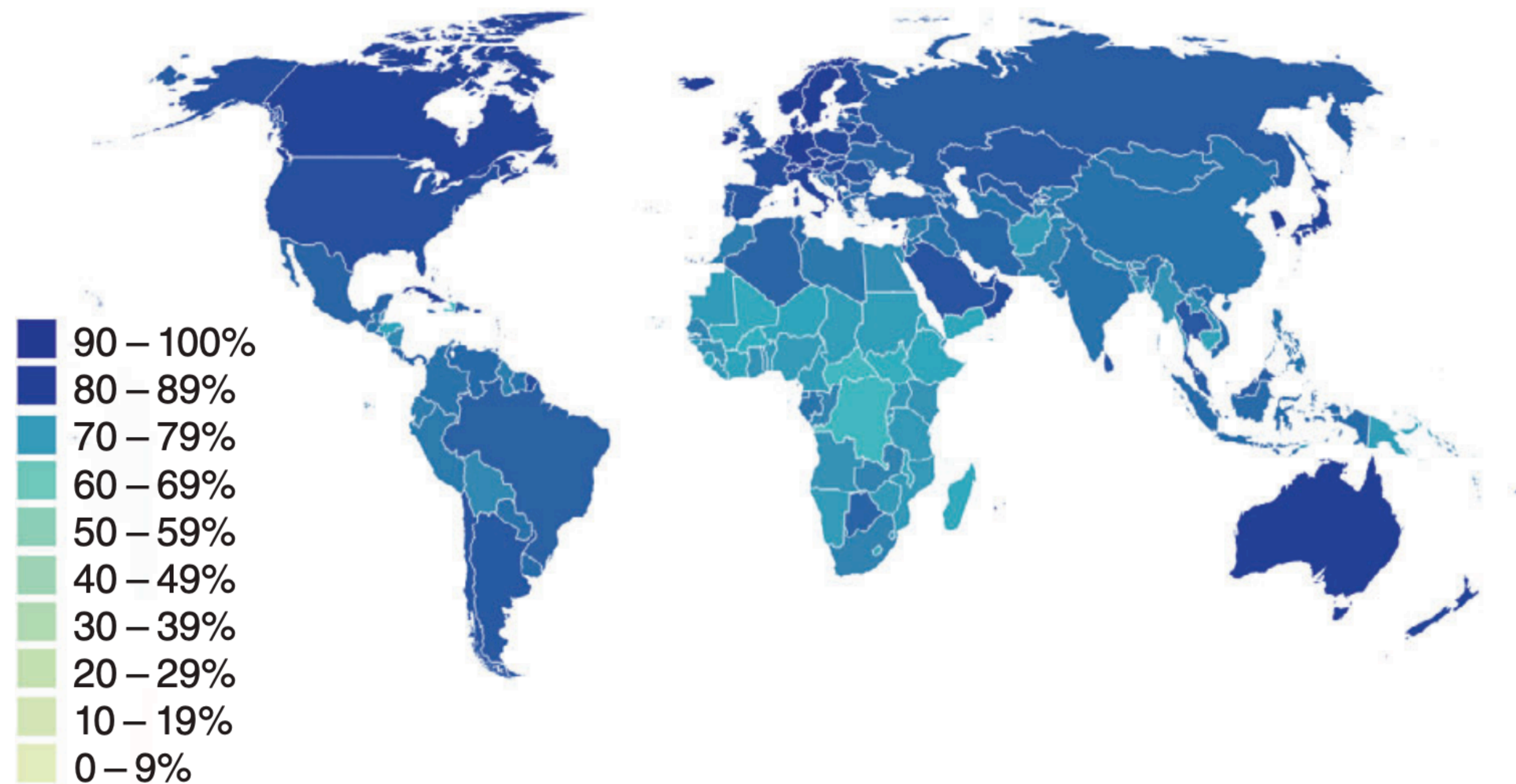
SIG Presentation

Joint work with Eojin Han, Kristian Singh, and Omid Nohadani



Deferred Surgeries due to COVID-19

- 12-week cancellation rates of surgery for benign disease (March to May 2020)



Source: COVIDSurg Collaborative (2020) Elective surgery cancellations due to the COVID-19 pandemic: global predictive modeling to inform surgical recovery plans. British Journal of Surgery, 107(11): 1440-1449.

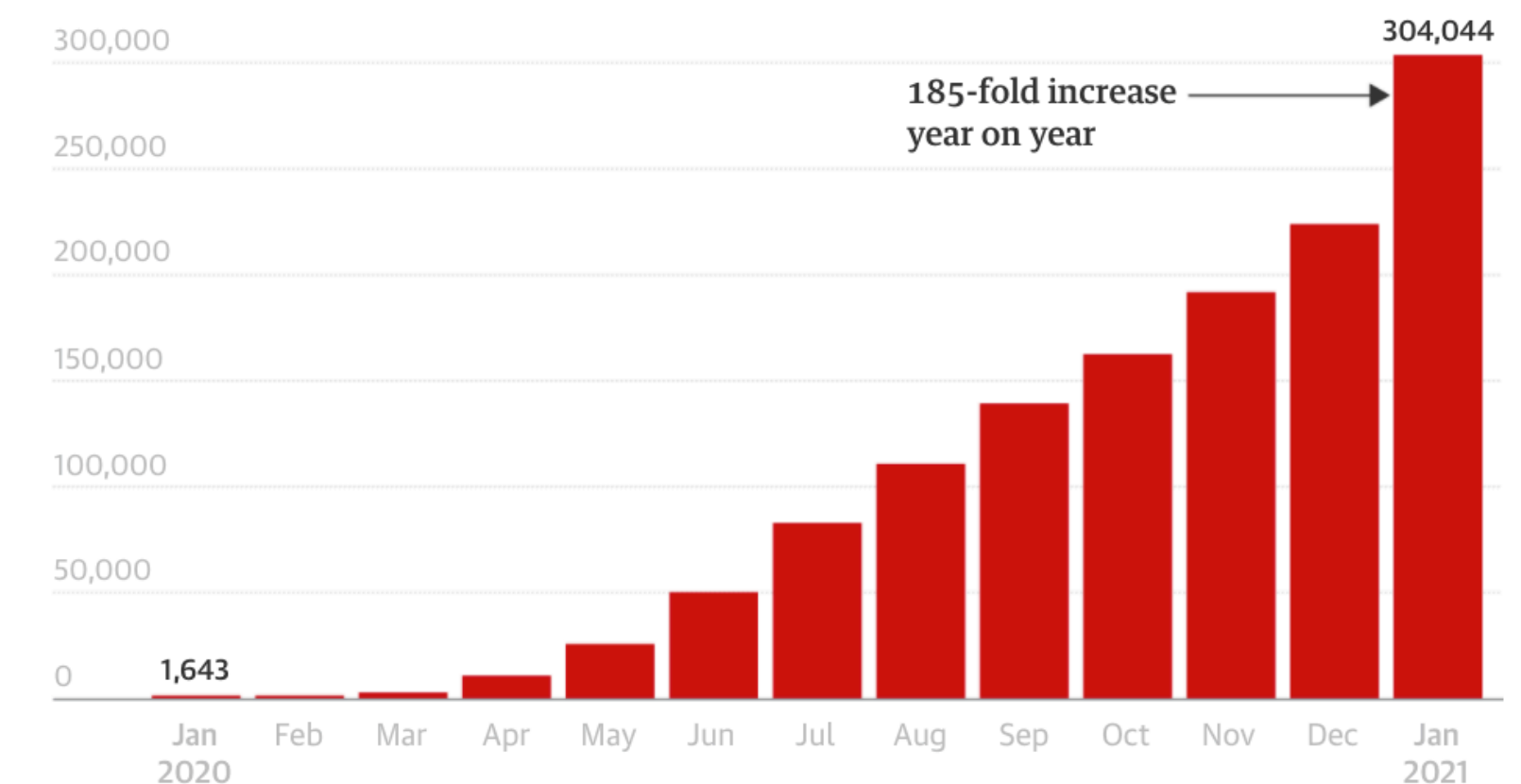
The Guardian

New Covid wave could worsen NHS surgery backlog, experts warn

Relaxation of rules and sharp rise in B.1.617.2 variant cause concern, as millions wait for hospital treatment

There has been a huge increase in the number of people waiting more than a year for NHS care since the start of the Covid pandemic

Number of people waiting over 52 weeks for NHS treatment



Source: D. Campbell. 'A truly frightening backlog': ex-NHS chief warns of delays in vital care. The Guardian, April 2, 2021 / N. Davis and D. Campbell. New Covid wave could worsen NHS surgery backlog, experts warn. The Guardian, May 20, 2021.

Cost of Deferred Elective Surgeries

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- Potentially, worst health care outcomes for patients due to delayed treatment
- Increased financial costs for hospitals and insurers due to worsened diseases
- Significant financial loss for hospitals
 - Average monthly loss of revenue of the U.S. hospitals is \$50.7 billion for March-June 2020 (Meredith et al. 2020).
 - Elective surgeries account for 43% of gross revenue of the U.S. hospitals (Tonna et al. 2020).

Source: Meredith, High, and Freischlag (2020) Preserving elective surgeries in the COVID-19 pandemic and the future. JAMA 324(17):1725-1726. Tonna, Hanson, Cohan, McCrum, Horns, Brooke, Das, Kelly, Campbell, and Hotaling (2020) Balancing revenue generation with capacity generation: case distribution, financial impact and hospital capacity changes from cancelling or resuming elective surgeries in the US during COVID-19. BMC Health Services Research 20(1):1-7.

Capacity Management for Deferred Surgeries

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 - Improved health outcomes
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 - ➔ **Silver Bullet:** An *optimization-based methodology* to dynamically manage surgical capacity for deferred surgeries, while balancing the profit with service requirements.

Problem Set-up

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Expansion Decisions

- $\mathbf{C}_B = (C_{B,1}, \dots, C_{B,t})$
- $\mathbf{C} = (C_1, \dots, C_t)$

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Surgeries and Deferrals

- $\mathbf{u}_t = (u_t^{(-L)}, \dots, u_t^{(t)})$: deferred surgeries.
- $u_t^{(\tau)}$: surgeries scheduled at τ and carried out at t .
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Demand & capacity constraints

$$x_t^{(\tau)} \leq u_t^{(\tau)} \quad \sum_{\tau=-L}^t x_t^{(\tau)} \leq \hat{C}_t + C_{B,t} + C_t$$

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$$(\mathbf{C}_B, \mathbf{C}) \in \mathcal{C}$$

Expansion constraints

Dynamic Programming Formulation

- Cost at time t :

$$H_t(C_{B,t}, C_t, \mathbf{u}_t, \mathbf{x}_t, \mathbf{w}_t) := b_{B,t}(\hat{C}_t + C_{B,t}) + b_t C_t \\ + c_t \sum_{\tau=-L}^t x_t^{(\tau)} + \sum_{\tau=-L}^t p_{t-\tau}(u_t^{(\tau)} - x_t^{(\tau)} - w_t^{(\tau)}) + \sum_{\tau=-L}^t f_{t-\tau} w_t^{(\tau)}$$

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- Dynamic programming (DP) model:

$$\min_{C_B, C_1} \mathbb{E}_{d_1} \left[\min_{\mathbf{x}_1} \mathbb{E}_{\mathbf{w}_1} \left[H_1(\cdot) + \min_{C_2} \mathbb{E}_{d_2} \left[\min_{\mathbf{x}_2} \mathbb{E}_{\mathbf{w}_2} \left[H_2(\cdot) + \dots + \min_{C_T} \mathbb{E}_{d_T} \left[\min_{\mathbf{x}_T} \mathbb{E}_{\mathbf{w}_T} \left[H_T(\cdot) \right] \right] \right] \dots \right] \right] \right]$$

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 - Model difficult to solve

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- Robust Optimization (RO)
 - Uncertainties are described via polyhedral and box sets.
 - Decisions are made to minimize the worst-case cost.
 - Introduce the *tree of uncertainty products* and leverage McCormick relaxations to handle multilinear uncertainty.

$$\mathcal{U}_w(\mathbf{u}_T, \mathbf{x}_T) =$$
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Overall Problem

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$$\min_{\mathbf{C}_t(\cdot), \mathbf{x}_t(\cdot)} \max_{\theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}} \sum_{t \in [T]} G_t(\mathbf{C}_t(\theta_{[t-1]}, \mathbf{d}_{[t-1]}), \mathbf{x}_{[t]}(\theta_{[t-1]}, \mathbf{d}_{[t]}), \theta_{[t]}, \mathbf{d}_{[t]})$$

$$\text{s.t.} \quad \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^{t-1} \theta_k \right) x_{t'}^{(\tau)}(\theta_{[t'-1]}, \mathbf{d}_{[t']}) \leq \left(\prod_{k=\max(\tau, 1)}^{t-1} \theta_k \right) \mathbf{d}_\tau \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, \tau \in [-L : t], t \in [T]$$

$$\sum_{\tau \in [-L : t]} x_t^{(\tau)}(\theta_{[t-1]}, \mathbf{d}_{[t]}) \leq \hat{\mathbf{C}}_t + \mathbf{C}_{B,t} + \mathbf{C}_t(\theta_{[t-1]}, \mathbf{d}_{[t-1]}) \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, t \in [T]$$

$$\mathbf{x}_t(\theta_{[t-1]}, \mathbf{d}_{[t]}) \in \mathbb{R}_+^{t+L} \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, t \in [T]$$

$$(\mathbf{C}_B, \mathbf{C}_1, \mathbf{C}_2(\theta_1, \mathbf{d}_1), \dots, \mathbf{C}_T(\theta_{[T-1]}, \mathbf{d}_{[T-1]})) \in \mathcal{C} \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U},$$

where $G_t(\mathbf{C}_t, \mathbf{x}_{[t]}, \theta_{[t]}, \mathbf{d}_{[t]}) :=$

$$b_{B,t}(\hat{\mathbf{C}}_t + \mathbf{C}_{B,t}) + b_t \mathbf{C}_t + \sum_{\tau=-L}^t c_t x_t^{(\tau)} + \sum_{\tau=-L}^t f_{t-\tau} \left[\left(\prod_{k=\max(\tau, 1)}^{t-1} \theta_k \right) \mathbf{d}_\tau - \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^{t-1} \theta_k \right) x_{t'}^{(\tau)} \right] \\ + \sum_{\tau=-L}^t (p_{t-\tau} - f_{t-\tau}) \left[\left(\prod_{k=\max(\tau, 1)}^t \theta_k \right) \mathbf{d}_\tau - \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^t \theta_k \right) x_{t'}^{(\tau)} \right].$$

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Can be \mathbb{E} (stochastic), or $\sup \mathbb{E}$ (distributionally robust)

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$$\min_{\mathbf{C}_t(\cdot), \mathbf{x}_t(\cdot)} \max_{\theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}} \sum_{t \in [T]} G_t(\mathbf{C}_t(\theta_{[t-1]}, \mathbf{d}_{[t-1]}), \mathbf{x}_{[t]}(\theta_{[t-1]}, \mathbf{d}_{[t]}), \theta_{[t]}, \mathbf{d}_{[t]})$$

$$\text{s.t.} \quad \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^{t-1} \theta_k \right) \mathbf{x}_{t'}^{(\tau)}(\theta_{[t'-1]}, \mathbf{d}_{[t']}) \leq \left(\prod_{k=\max(\tau, 1)}^{t-1} \theta_k \right) \mathbf{d}_\tau \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, \tau \in [-L : t], t \in [T]$$

$$\sum_{\tau \in [-L : t]} \mathbf{x}_t^{(\tau)}(\theta_{[t-1]}, \mathbf{d}_{[t]}) \leq \hat{\mathbf{C}}_t + \mathbf{C}_{B,t} + \mathbf{C}_t(\theta_{[t-1]}, \mathbf{d}_{[t-1]}) \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, t \in [T]$$

$$\mathbf{x}_t(\theta_{[t-1]}, \mathbf{d}_{[t]}) \in \mathbb{R}_+^{t+L} \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U}, t \in [T]$$

$$(\mathbf{C}_B, \mathbf{C}_1, \mathbf{C}_2(\theta_1, \mathbf{d}_1), \dots, \mathbf{C}_T(\theta_{[T-1]}, \mathbf{d}_{[T-1]})) \in \mathcal{C} \quad \forall \theta_{[T]} \in \Theta, \mathbf{d}_{[T]} \in \mathcal{U},$$

where $G_t(\mathbf{C}_t, \mathbf{x}_{[t]}, \theta_{[t]}, \mathbf{d}_{[t]}) :=$

$$b_{B,t}(\hat{\mathbf{C}}_t + \mathbf{C}_{B,t}) + b_t \mathbf{C}_t + \sum_{\tau=-L}^t c_t \mathbf{x}_t^{(\tau)} + \sum_{\tau=-L}^t f_{t-\tau} \left[\left(\prod_{k=\max(\tau, 1)}^{t-1} \theta_k \right) \mathbf{d}_\tau - \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^{t-1} \theta_k \right) \mathbf{x}_{t'}^{(\tau)} \right] \\ + \sum_{\tau=-L}^t (p_{t-\tau} - f_{t-\tau}) \left[\left(\prod_{k=\max(\tau, 1)}^t \theta_k \right) \mathbf{d}_\tau - \sum_{t'=\max(\tau, 1)}^t \left(\prod_{k=t'}^t \theta_k \right) \mathbf{x}_{t'}^{(\tau)} \right].$$

Multilinear uncertainty

Multilinear Uncertainty Terms

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- Two sources of uncertainty

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Departure

$$\mathcal{U}_w(\mathbf{u}_T, \mathbf{x}_T) = \{\mathbf{w}_t \mid \mathbf{w}_t = \rho_t(\mathbf{u}_t - x_t), \boldsymbol{\rho} \in \mathcal{U}_\rho\}$$

Non departed

$$u_t^{(\tau)} = (1 - \rho_{t-1})(u_{t-1}^{(\tau)} - x_{t-1}^{(\tau)}) \quad \forall \tau \in [-L : t - 1].$$

Telescoping

$$u_t^{(\tau)} = \left(\prod_{k=\max(\tau,1)}^{t-1} \theta_k \right) d_\tau - \sum_{t'=\max(\tau,1)}^{t-1} \left(\prod_{k=t'}^{t-1} \theta_k \right) x_{t'}^{(\tau)} \quad \forall \tau \in [-L : t], t \in [T],$$

Tree of Uncertainty Products

Tree of Uncertainty Products

- The problem consists of uncertain terms of the form

$$\sum_{k \in [K]} q^{(k)} \xi_k + \sum_{n \in [N]} q_g^{(n)} \prod_{i \in S_n} \xi_i \geq q_0 \quad \forall \xi \in \mathcal{U}$$

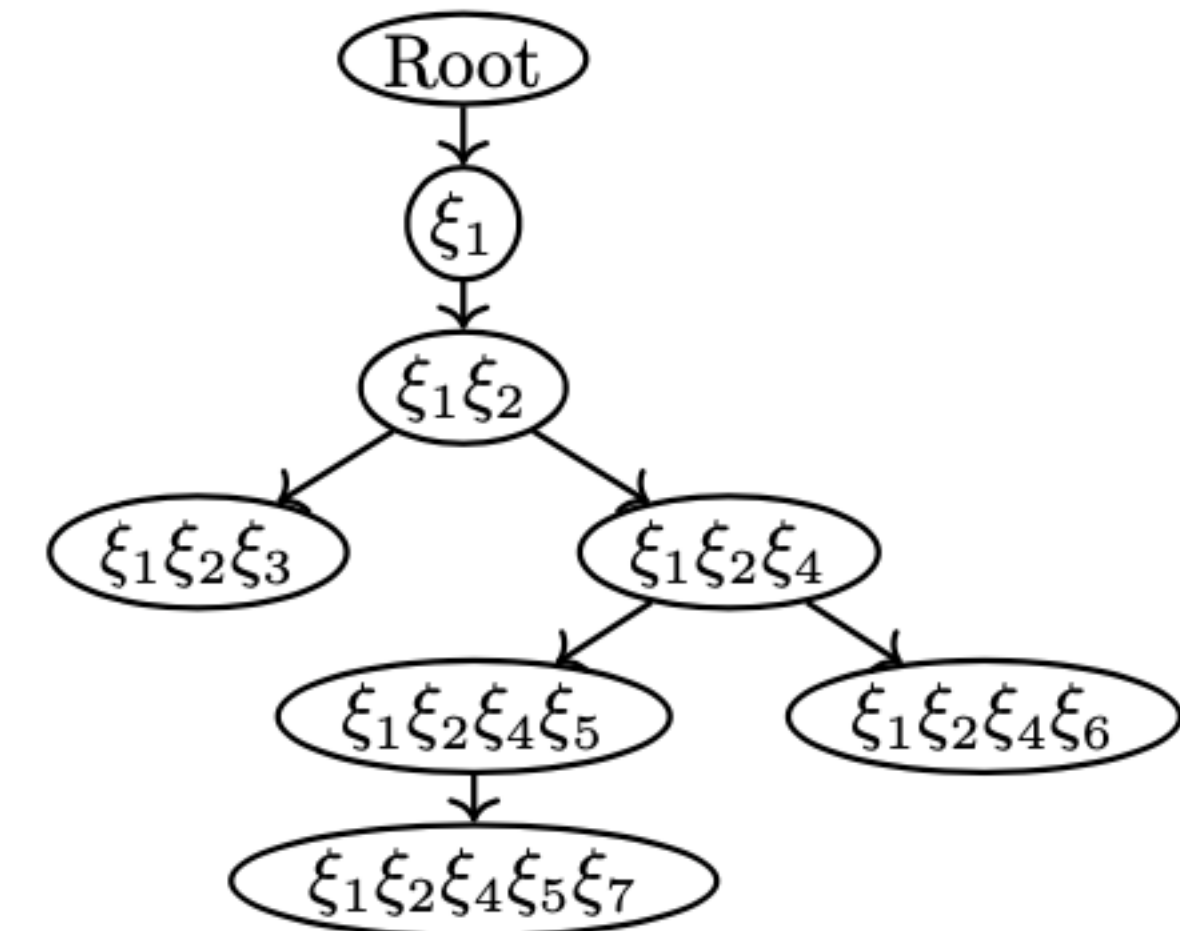
- This constraint involves sums of multilinear terms.

Tree of Uncertainty Products

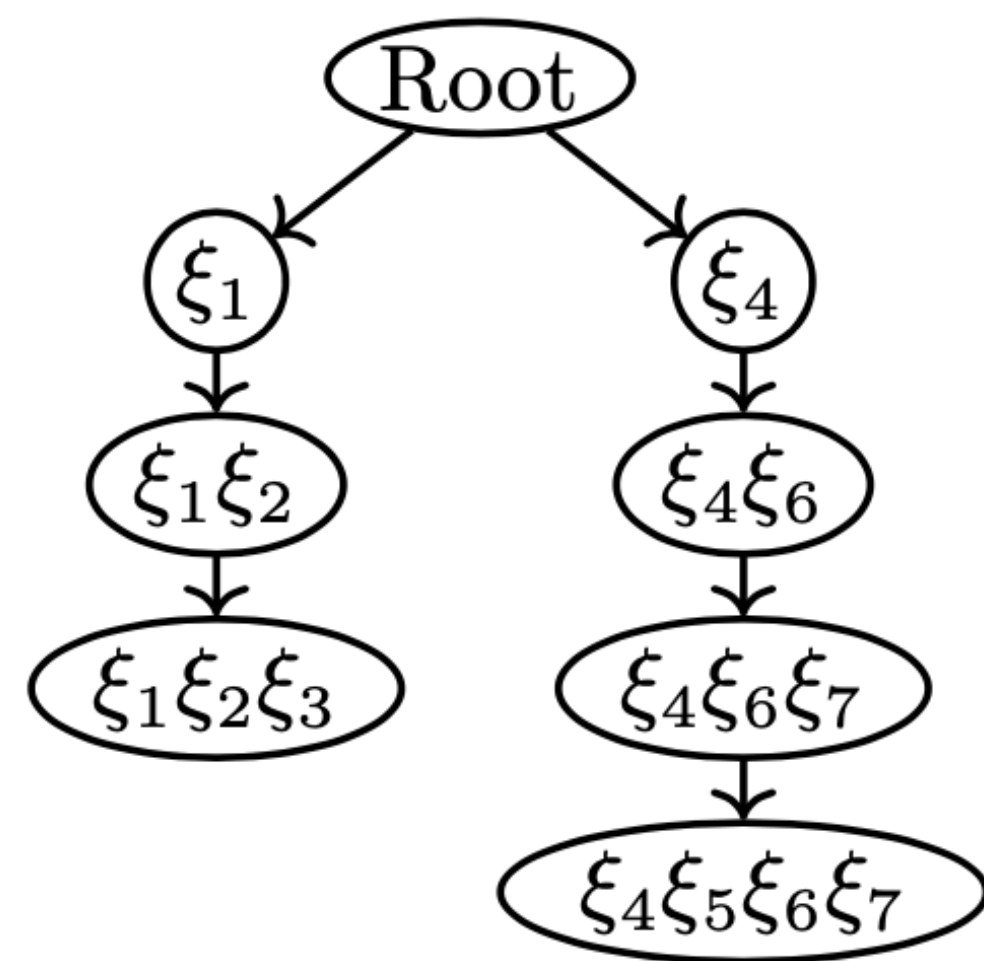
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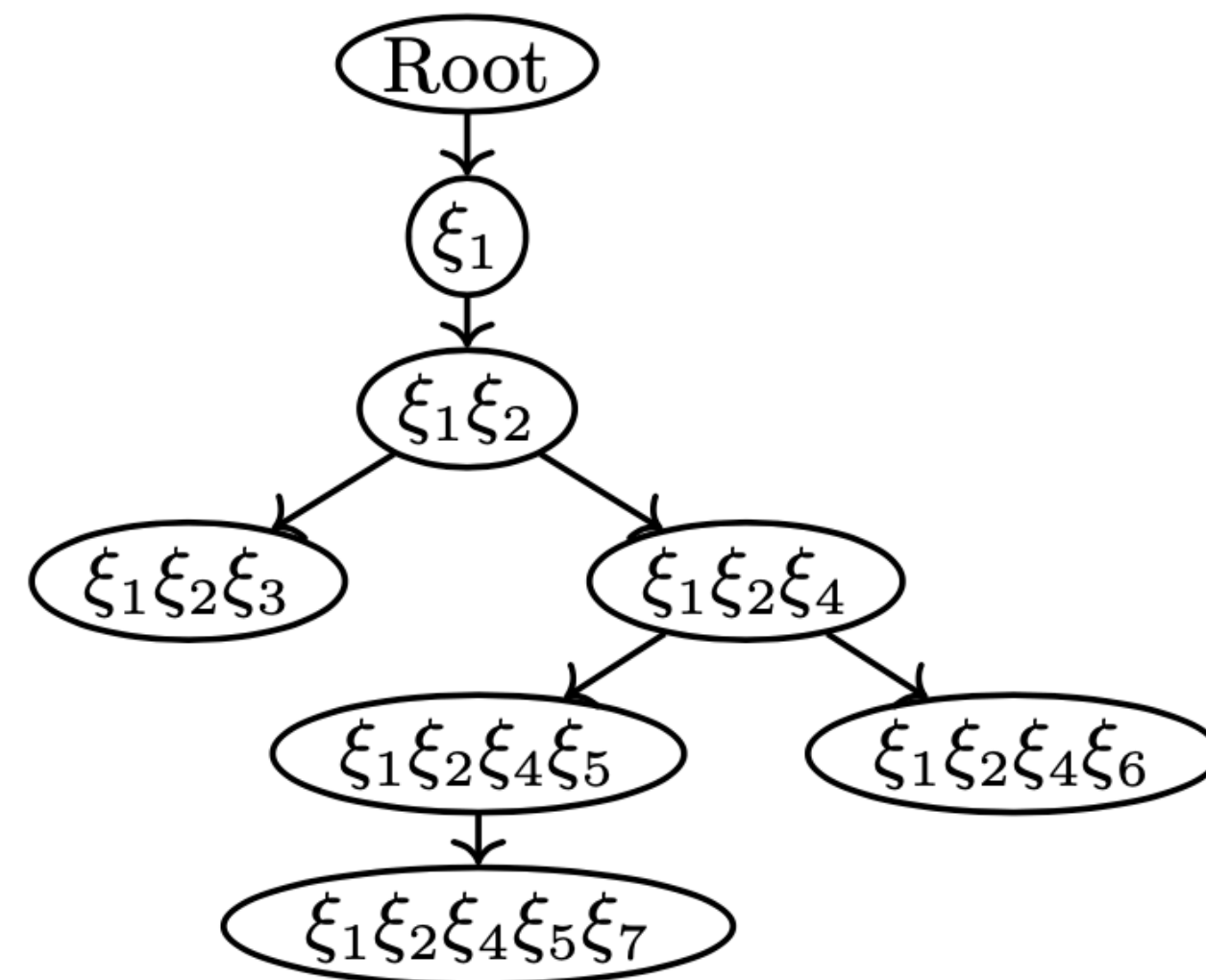
- This constraint involves sums of multilinear terms.
- We show that if
 - the multilinear products are in the form of leaves of tree, and
 - No two leaves without common ancestor share that uncertain componentthen the constraint is equivalent to its McCormick relaxation



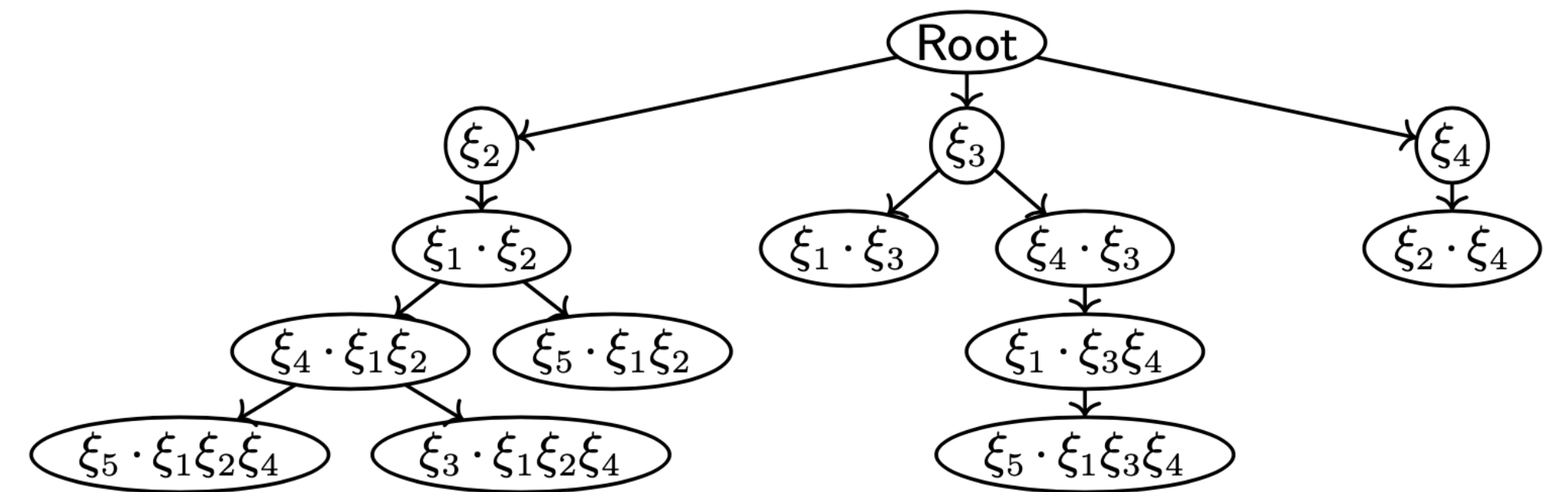
Tree of Uncertainty Products



Exact
No shared ξ



Exact
No shared ξ
except from ancestor

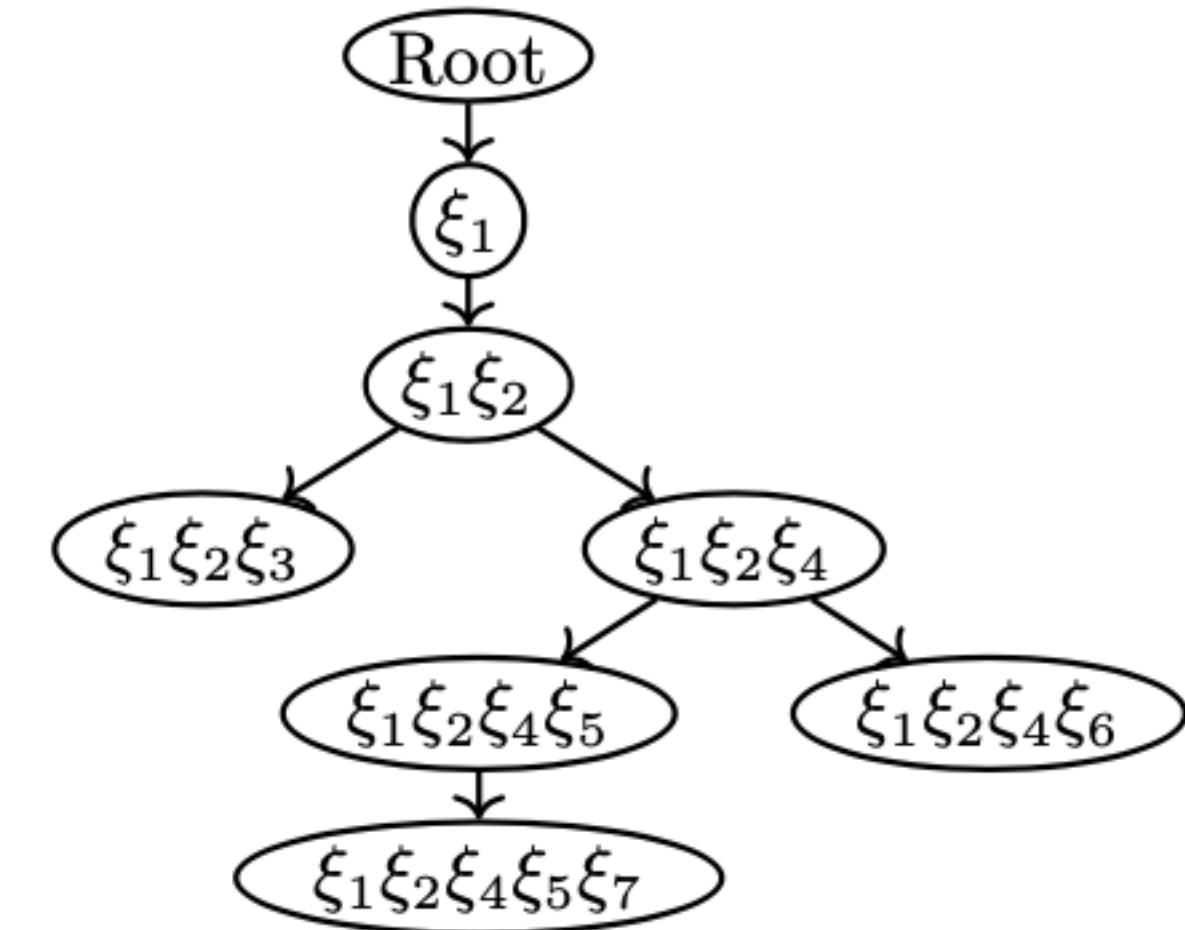


Not Exact
Shared ξ

Tree of Uncertainty Products

Tree of Uncertainty Products

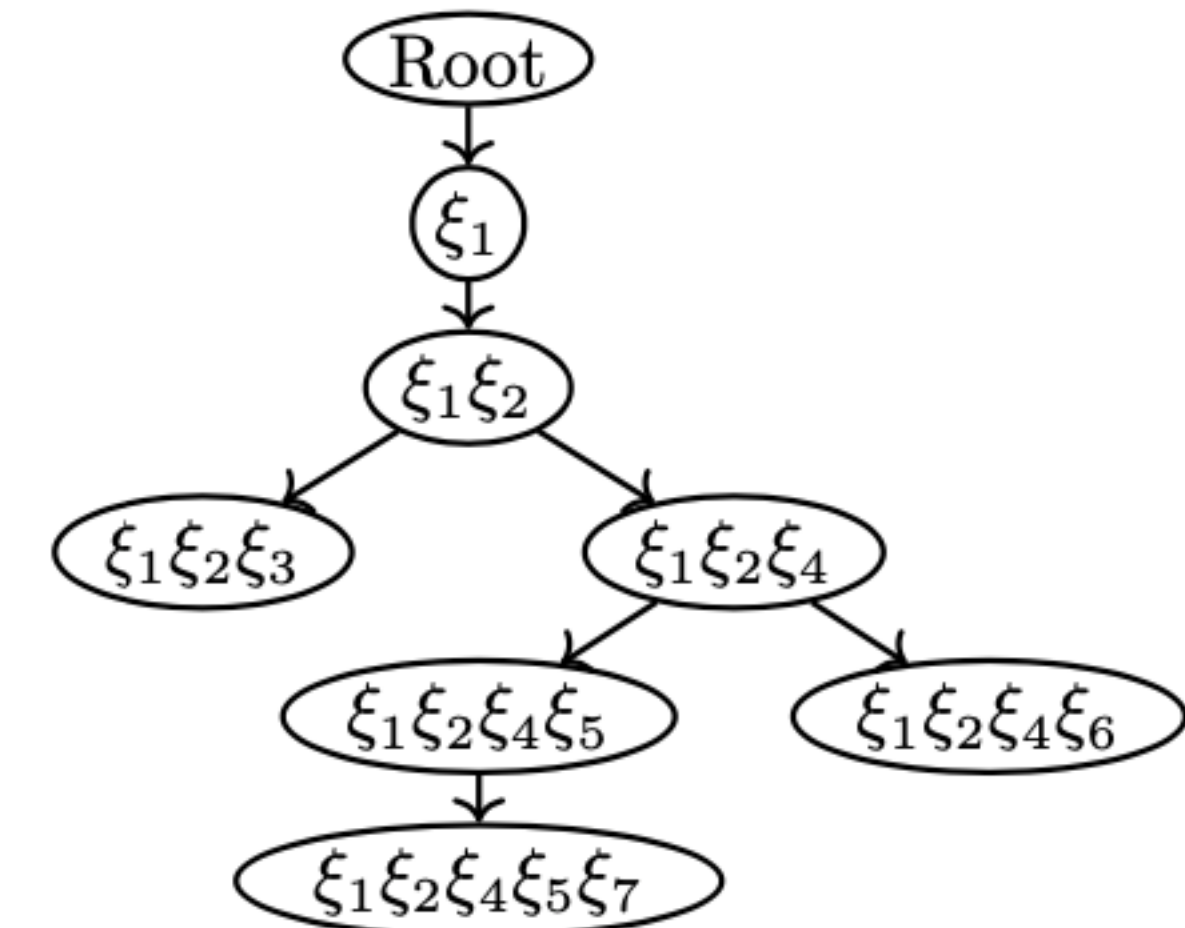
Key Result



Tree of Uncertainty Products

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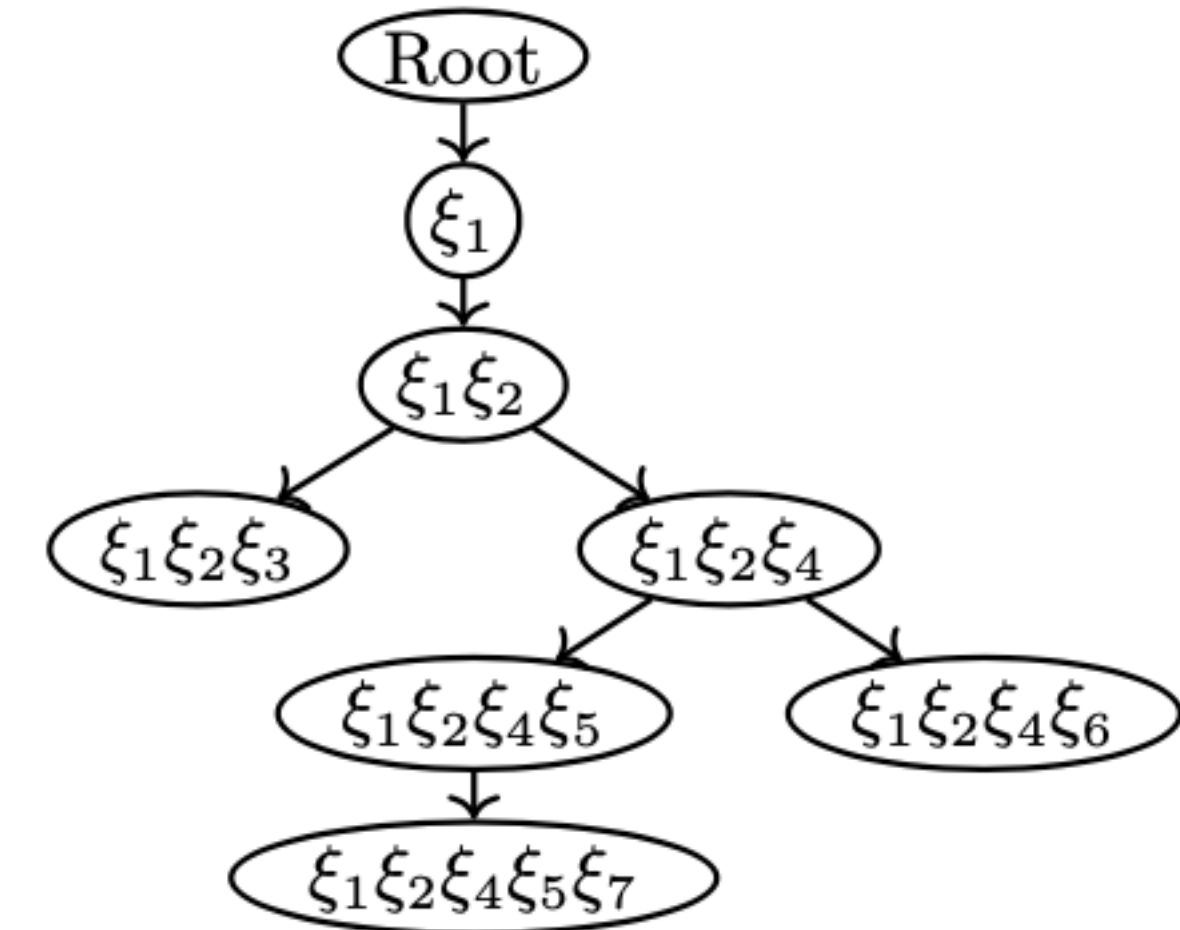
Tree of Uncertainty Products

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- Conservative Approximation

$$\sum_{k \in [K]} q^{(k)} \xi_k + \sum_{n \in [N]} q_g^{(n)} \eta_n \geq q_0 \quad \forall (\xi, \eta) \in \bar{\Xi}$$



$$\bar{\Xi} := \left\{ (\xi, \eta) \in \mathbb{R}^{K+N} \left| \begin{array}{ll} \xi \in \Xi & \\ \eta_i = \xi_{k_i^*} & \forall i: \ell(i) = 0 \\ \eta_i \geq \bar{\eta}_{\ell(i)} \xi_{k_i^*} + \bar{\xi}_{k_i^*} \eta_{\ell(i)} - \bar{\eta}_{\ell(i)} \bar{\xi}_{k_i^*} & \forall i: \ell(i) \neq 0 \\ \eta_i \geq \underline{\eta}_{\ell(i)} \xi_{k_i^*} + \underline{\xi}_{k_i^*} \eta_{\ell(i)} - \underline{\eta}_{\ell(i)} \underline{\xi}_{k_i^*} & \forall i: \ell(i) \neq 0 \\ \eta_i \leq \bar{\eta}_{\ell(i)} \xi_{k_i^*} + \bar{\xi}_{k_i^*} \eta_{\ell(i)} - \bar{\eta}_{\ell(i)} \bar{\xi}_{k_i^*} & \forall i: \ell(i) \neq 0 \\ \eta_i \leq \underline{\eta}_{\ell(i)} \xi_{k_i^*} + \underline{\xi}_{k_i^*} \eta_{\ell(i)} - \underline{\eta}_{\ell(i)} \underline{\xi}_{k_i^*} & \forall i: \ell(i) \neq 0 \end{array} \right. \right\}.$$

Tree of Uncertainty Products

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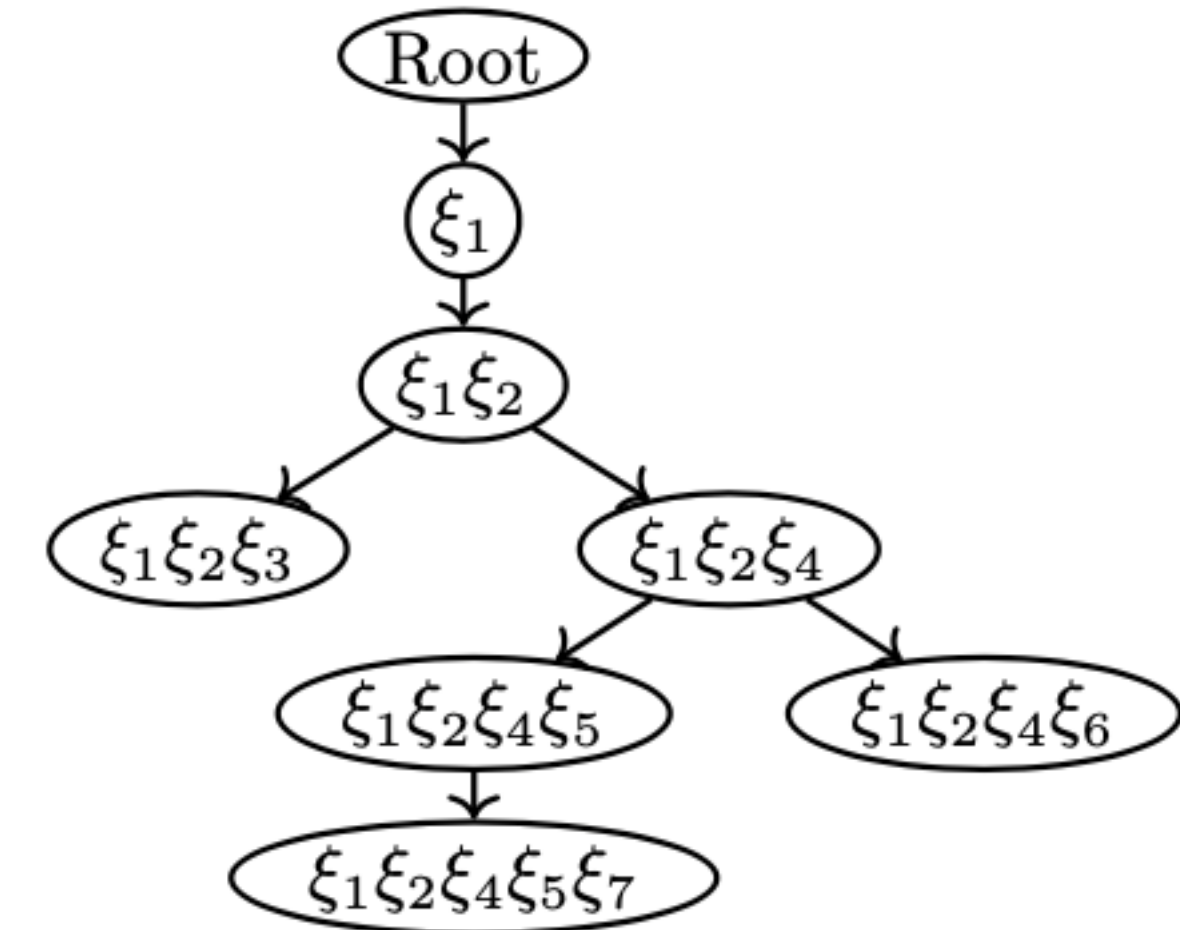
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- Exact Reformulation

- If \mathcal{U} is a box and
- Tree of Uncertainty Products has no overlap



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Outline of Methods

- Robust Optimization (RO)

- Uncertainties are described via polyhedral and box sets.
- Decisions are made to minimize the worst-case cost.
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- Numerical Experiments

Mean-MAD Ambiguity Sets

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- This allows us to reformulate the DRO problem as a Stochastic Optimization problem.
 - We solve this problem using Sample Average Approximation

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Multistage DRO \longrightarrow Multistage SO

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- Our analysis estimates current backlog as 4 months of average (pre-pandemic) monthly demand.
- Four methods are implemented and compared:
 - **RO**: robust optimization-based method
 - **DRO**: distributionally robust optimization-based method
 - Det60: temporally increase capacity by at most 60% (for ~7 months)
 - Det100: temporally increase capacity by at most 100% (for ~5 months)

Performance Improvement

Departure Level	DRO		RO		Det60		Det100	
	Mean	CVaR90	Mean	CVaR90	Mean	CVaR90	Mean	CVaR90
More Departure	-3969 (10.0)	-2882 (6.31)	-3833 (6.25)	-2927 (7.97)	-2740 (-24.1)	-1871 (-31.0)	-3608 (0.0)	-2711 (0.0)

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Performance Improvement

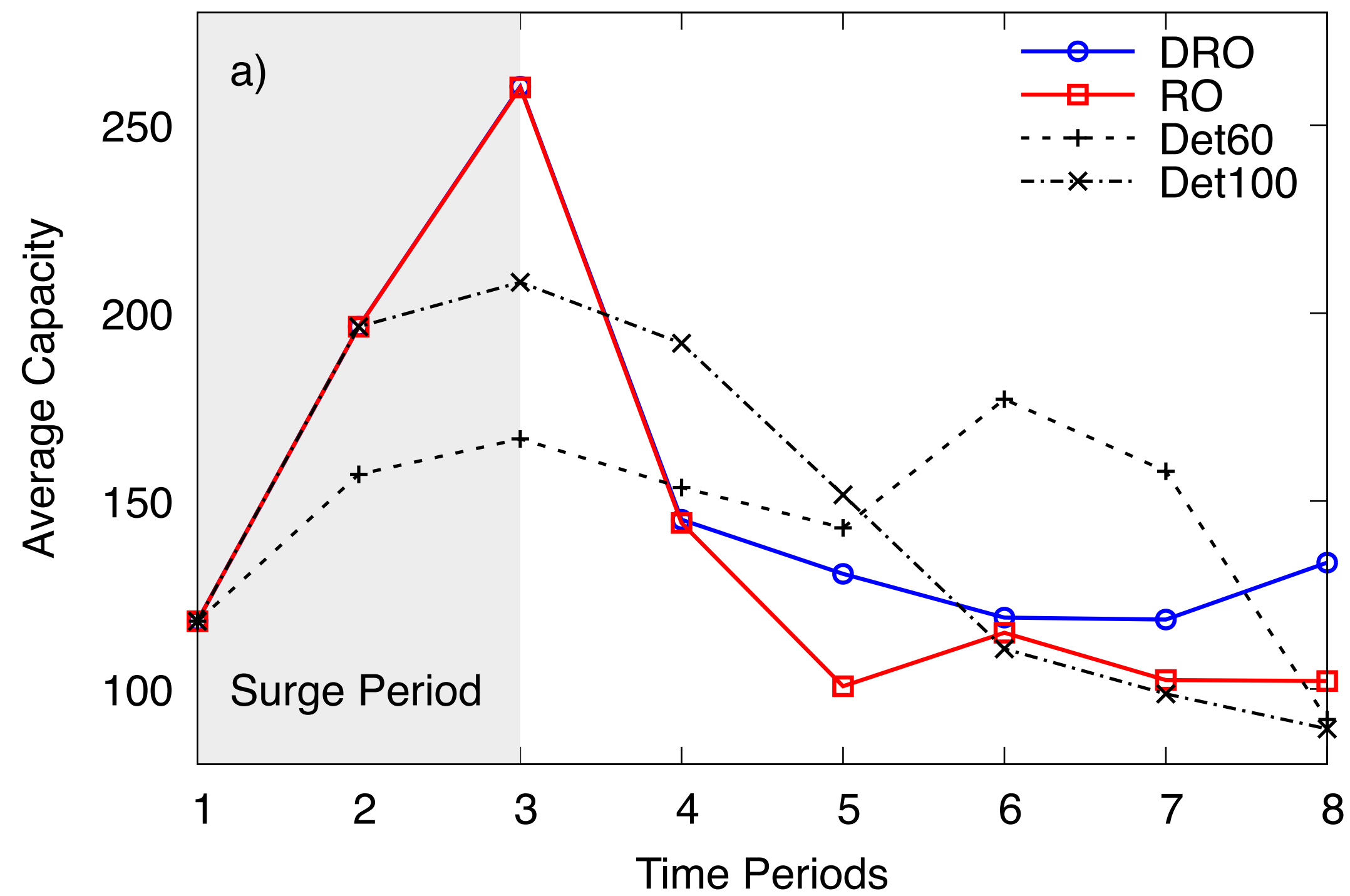
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Less Departure	-5078 (7.02)	-4284 (5.49)	-4906 (3.39)	-4306 (6.03)	-4078 (-14.1)	-3446 (-15.1)	-4745 (0.0)	-4061 (0.0)

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Structure of Expansion Policies

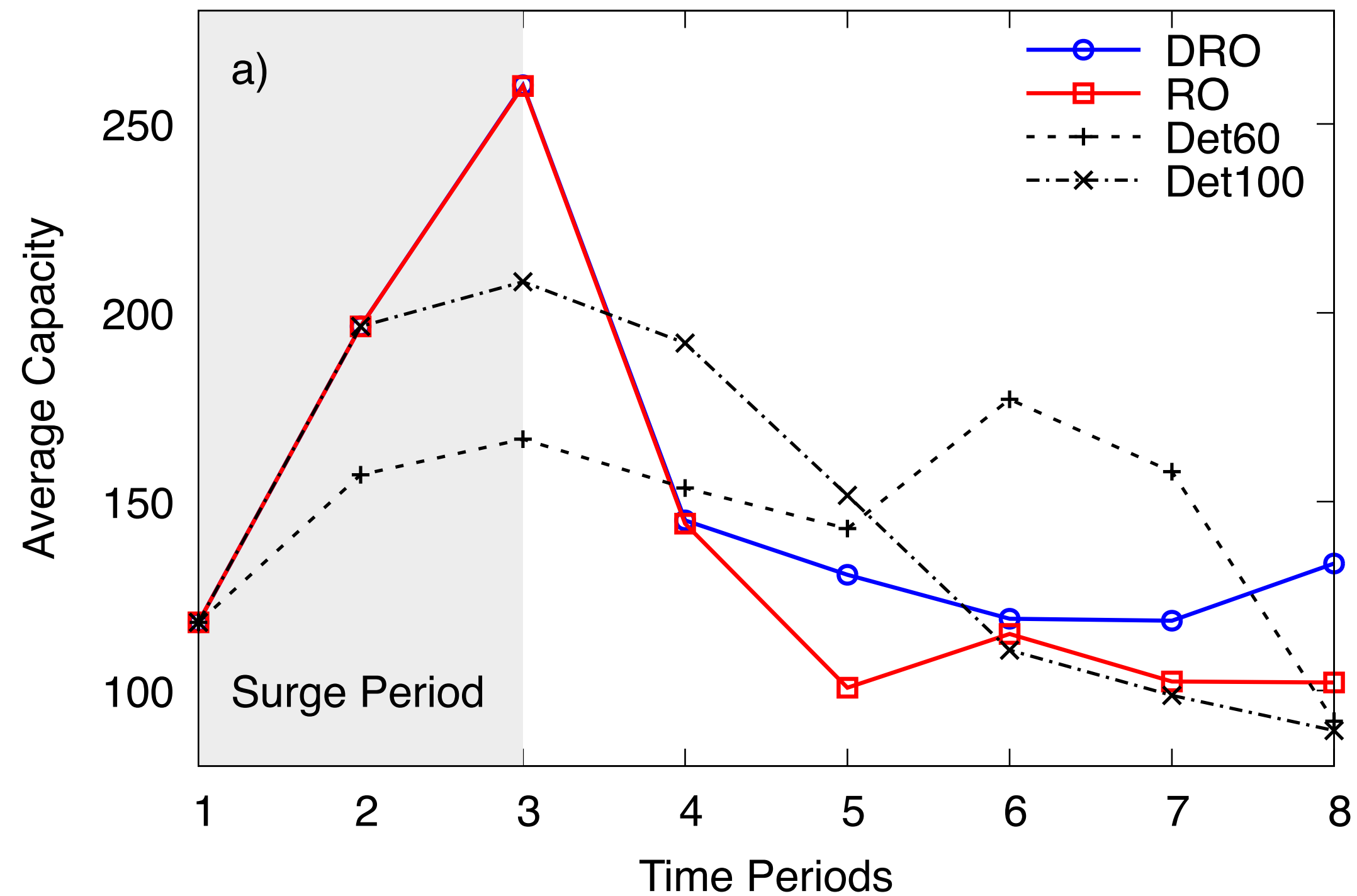
Structure of Expansion Policies

a) More Departure



Structure of Expansion Policies

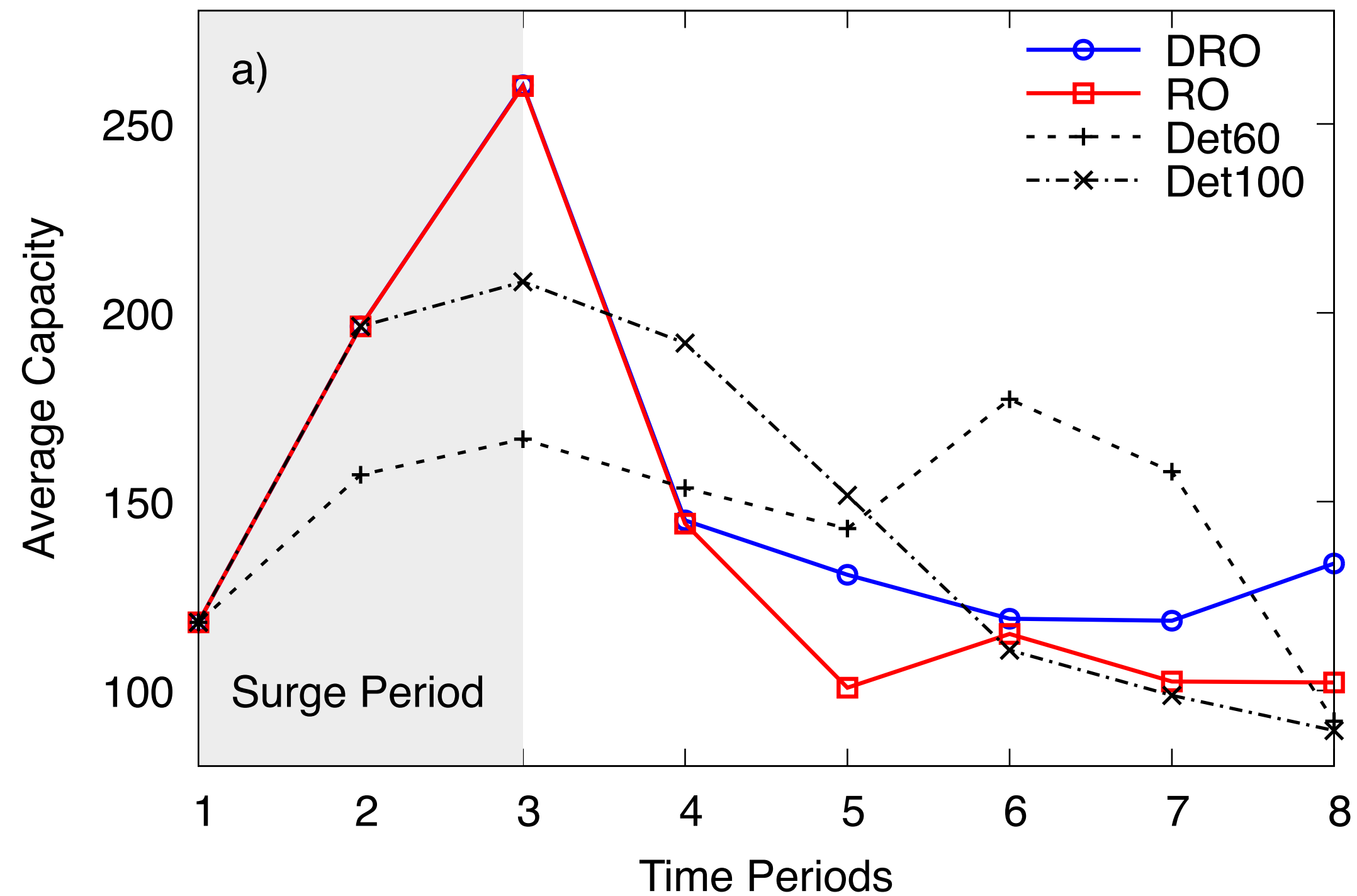
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- Both **RO** and **DRO** keep maximum capacity for the first three months (surge period).

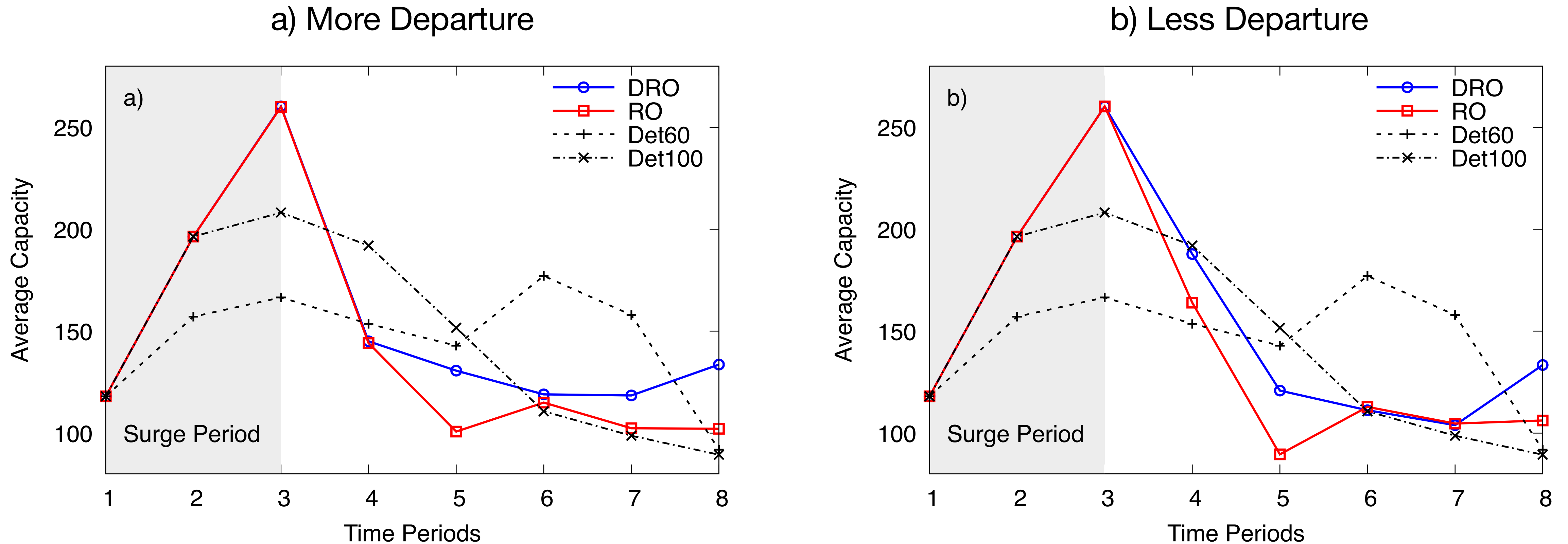
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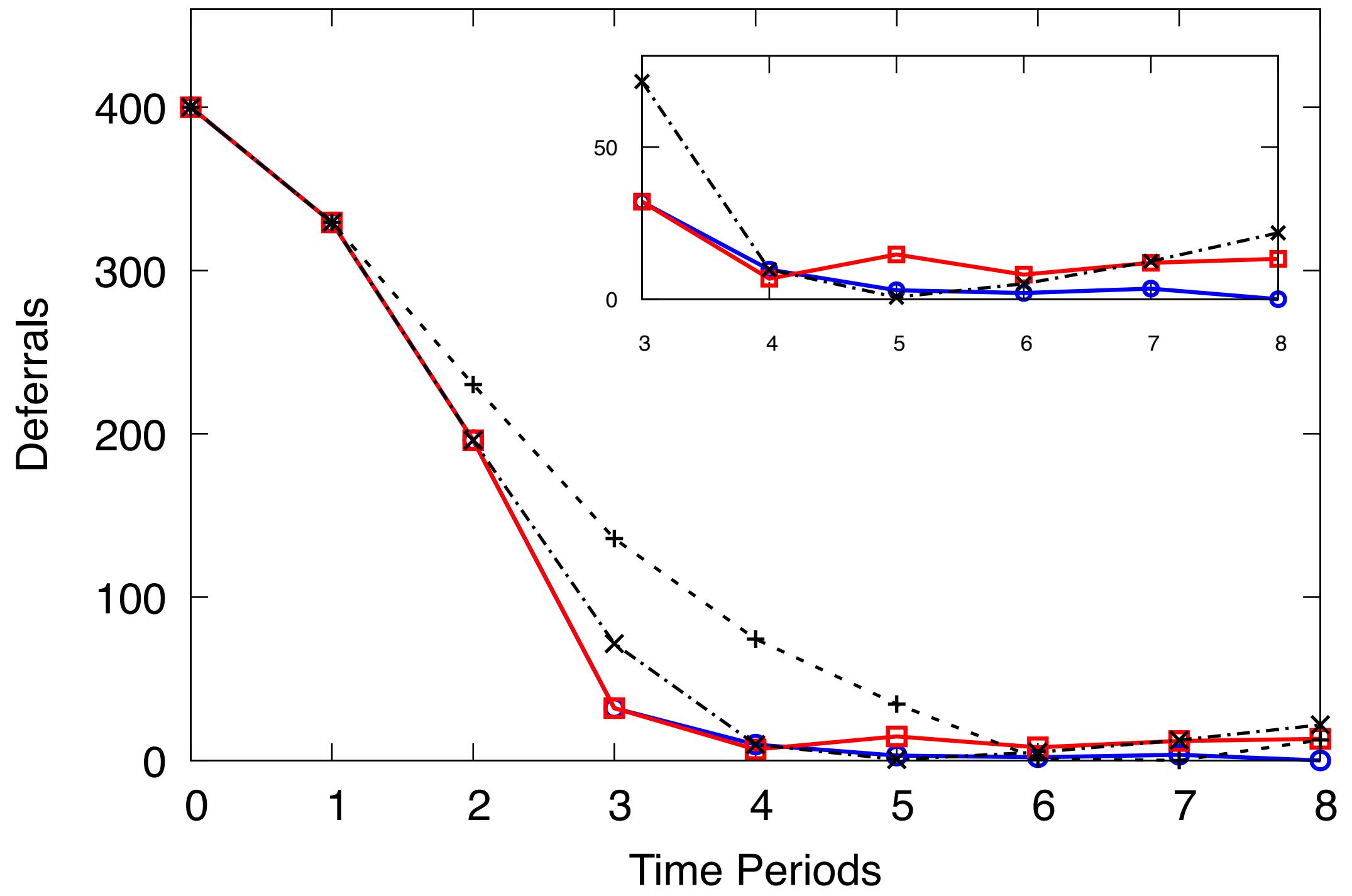


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Deferred and Departed Patients

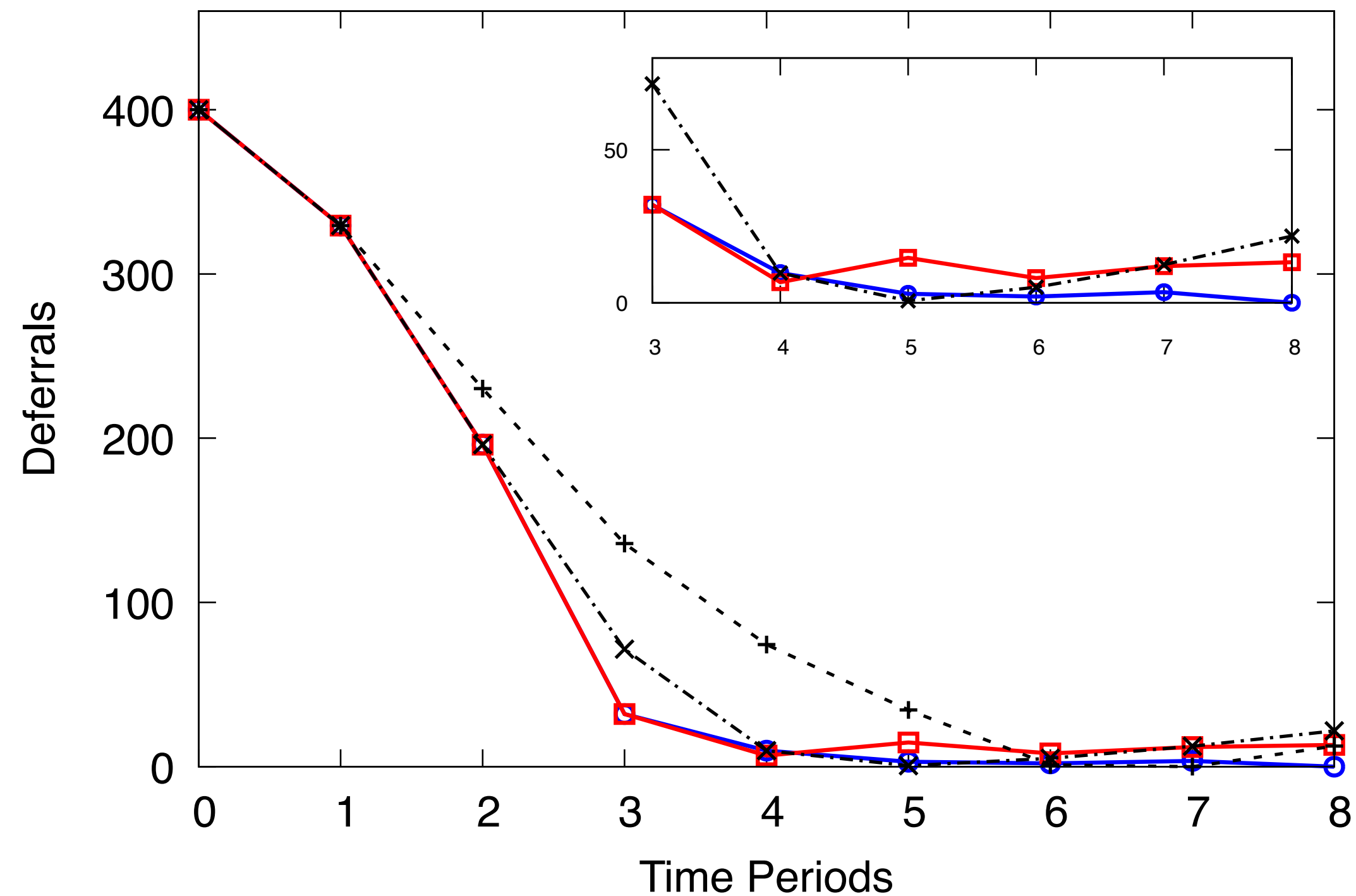
Deferred and Departed Patients

Deferred Patients over Time



Deferred and Departed Patients

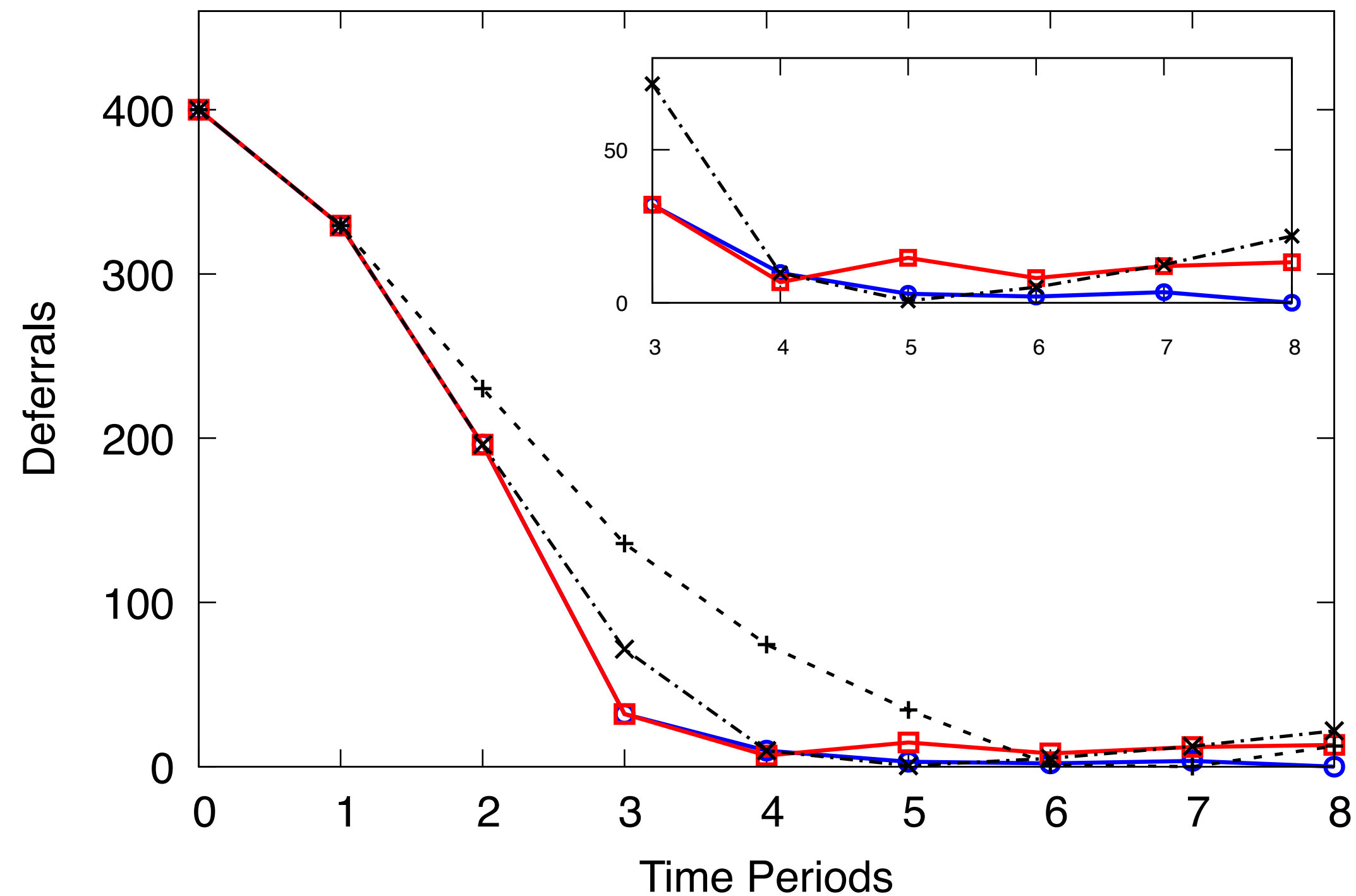
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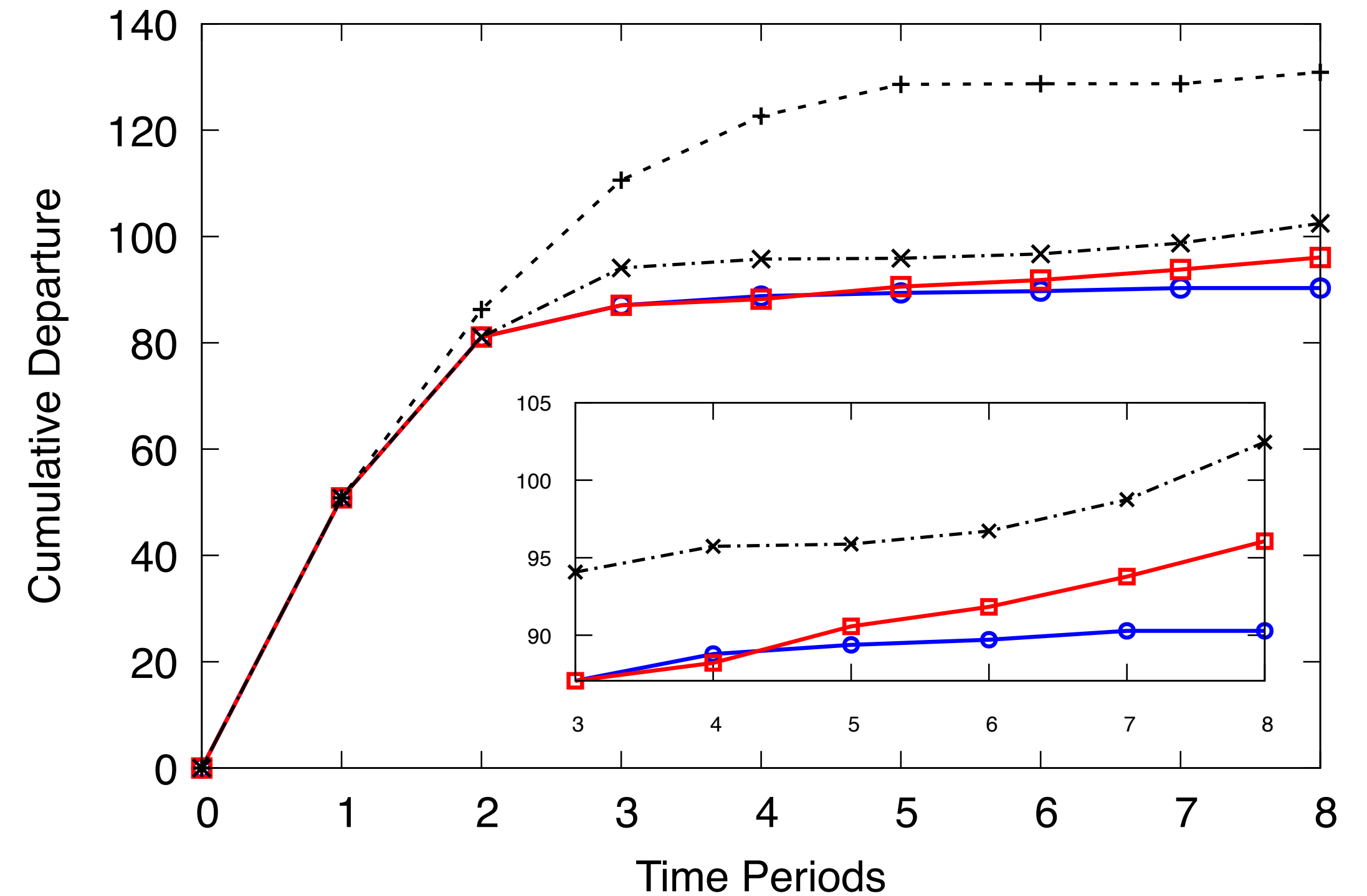
- Both **RO** and **DRO** policies achieve less numbers of deferrals and departures than deterministic policies.

Deferred and Departed Patients

Deferred Patients over Time



Cumulative Departure over Time



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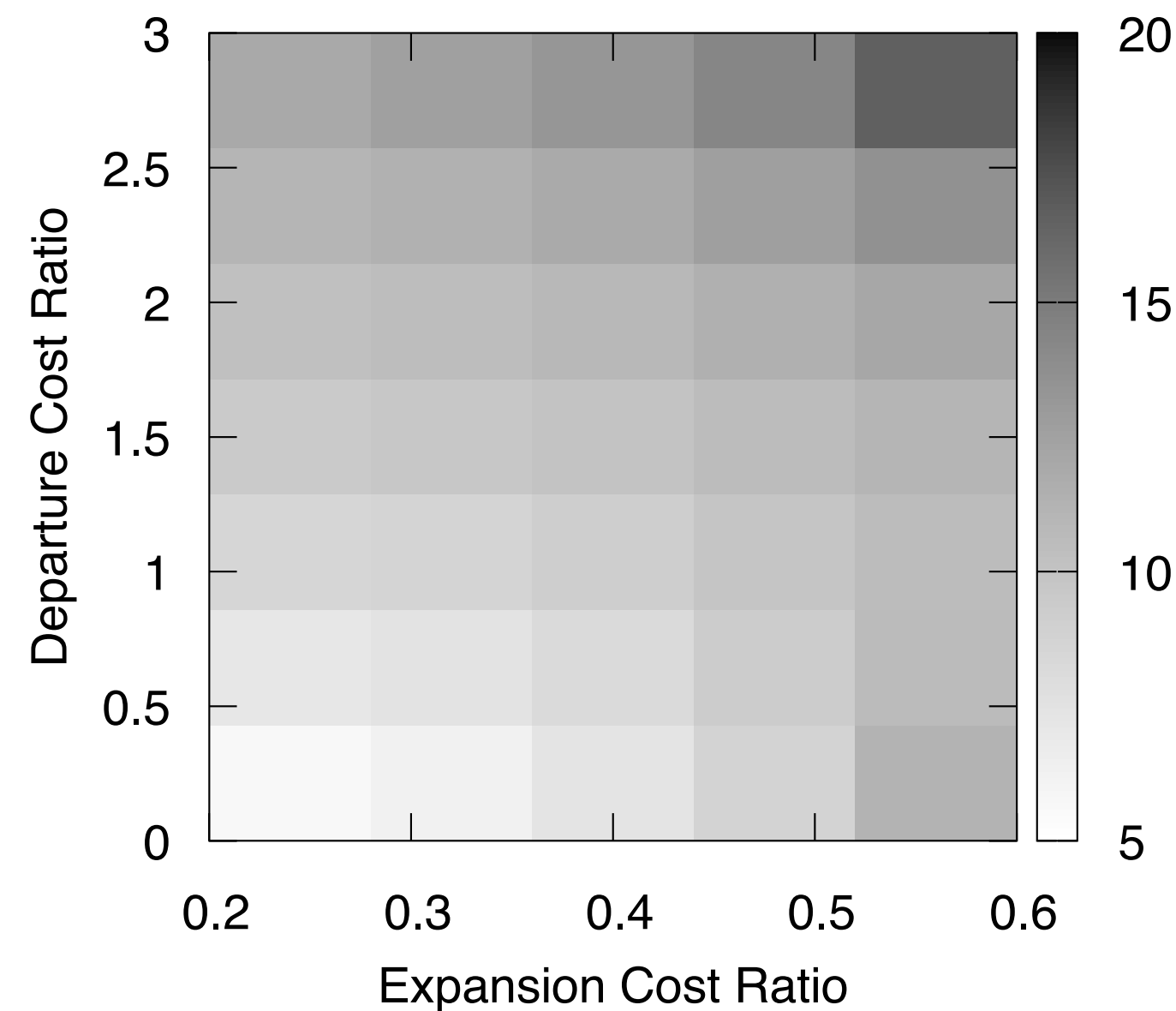
Comparison of Policies

	Lower demand (Mean 94)			Nominal demand (Mean 100)			Higher demand (Mean 106)		
	Static	Hybrid	Dynamic	Static	Hybrid	Dynamic	Static	Hybrid	Dynamic
RO	7.17%	8.91%	11.15%	5.61%	6.25%	9.90%	6.31%	7.89%	10.29%
DRO	2.61%	4.11%	4.36%	10.29%	10.00%	13.31%	11.12%	10.65%	13.10%
Det60	-23.8%	-24.2%	-24.9%	-25.6%	-24.1%	-23.3%	-27.4%	-26.6%	-26.2%

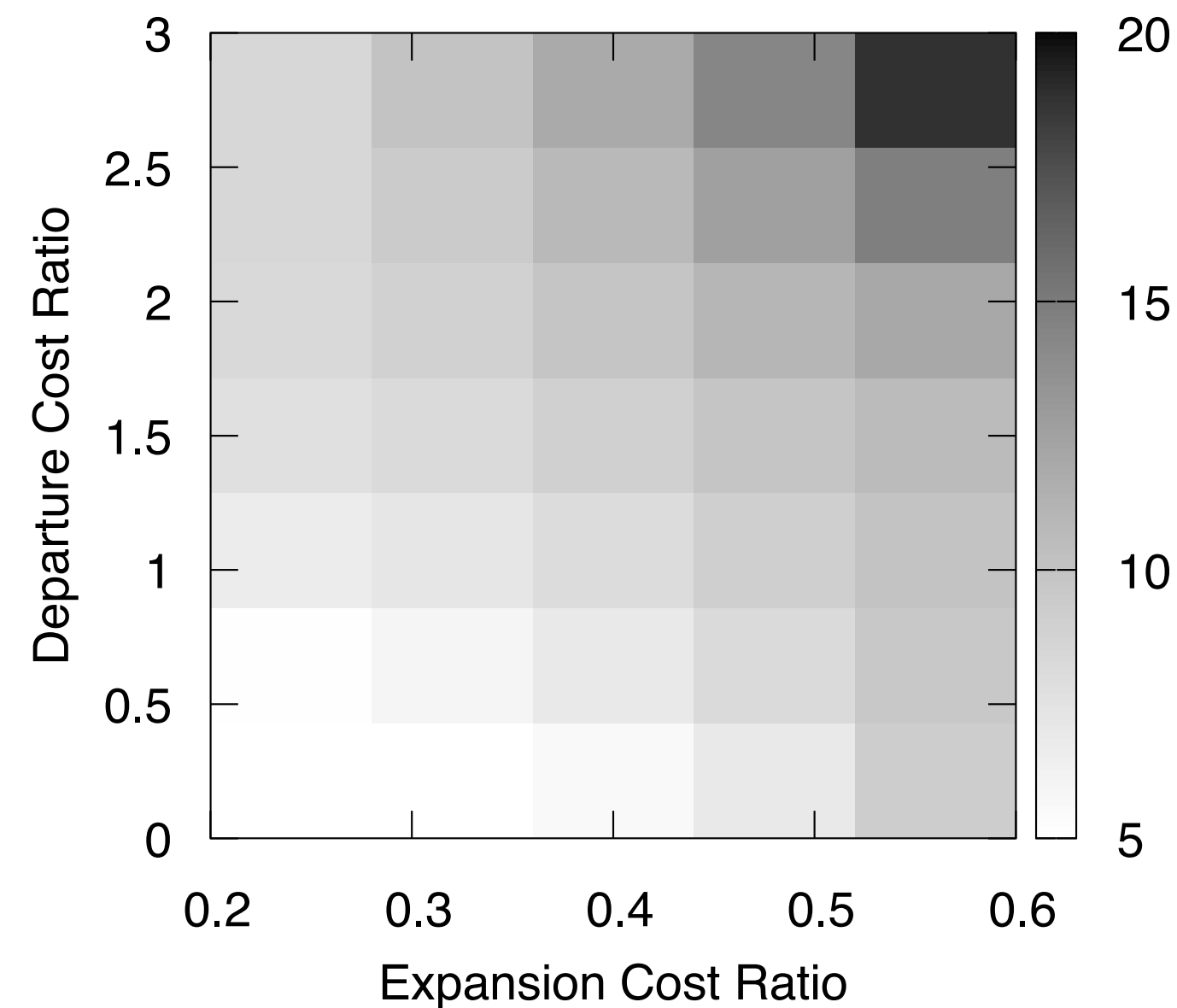
- Both **RO** and **DRO** policies improve over the deterministic policies
- **RO** is robust to higher and lower demand scenarios, but **DRO** is only guaranteed to protect against high demand settings.

Analysis of Outcomes

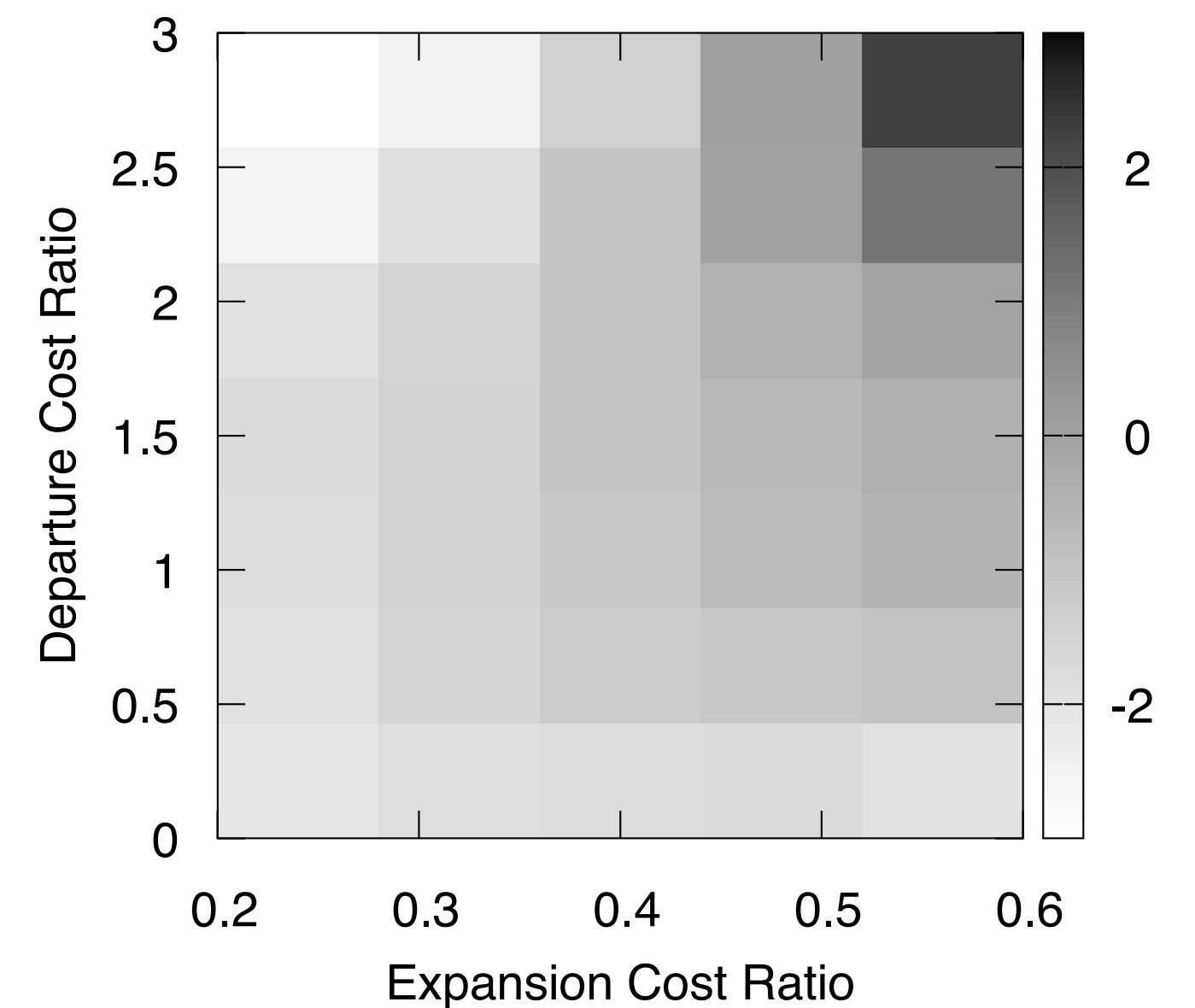
- Objective improvement (in percentage) over deterministic policies for different costs



(a) Heatmap of **DRO**



(b) Heatmap of **RO**

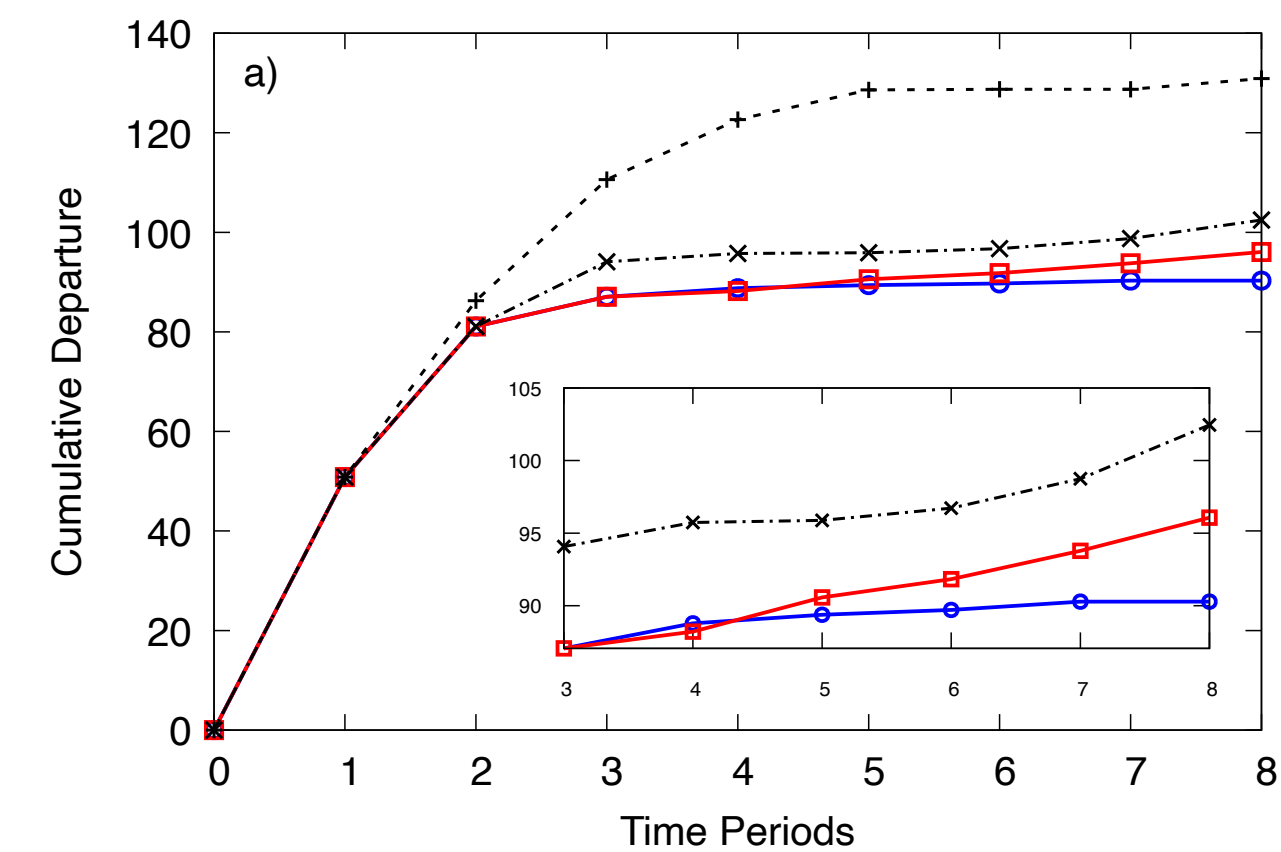
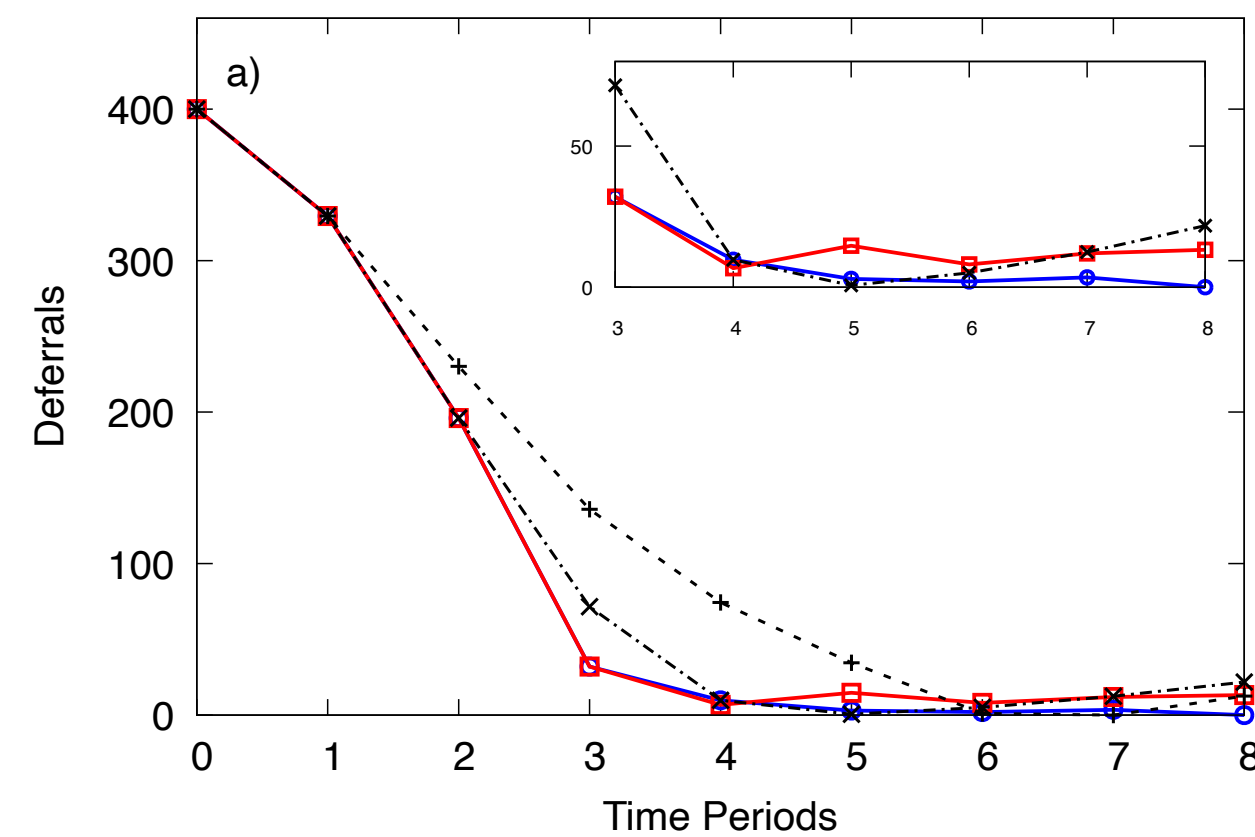
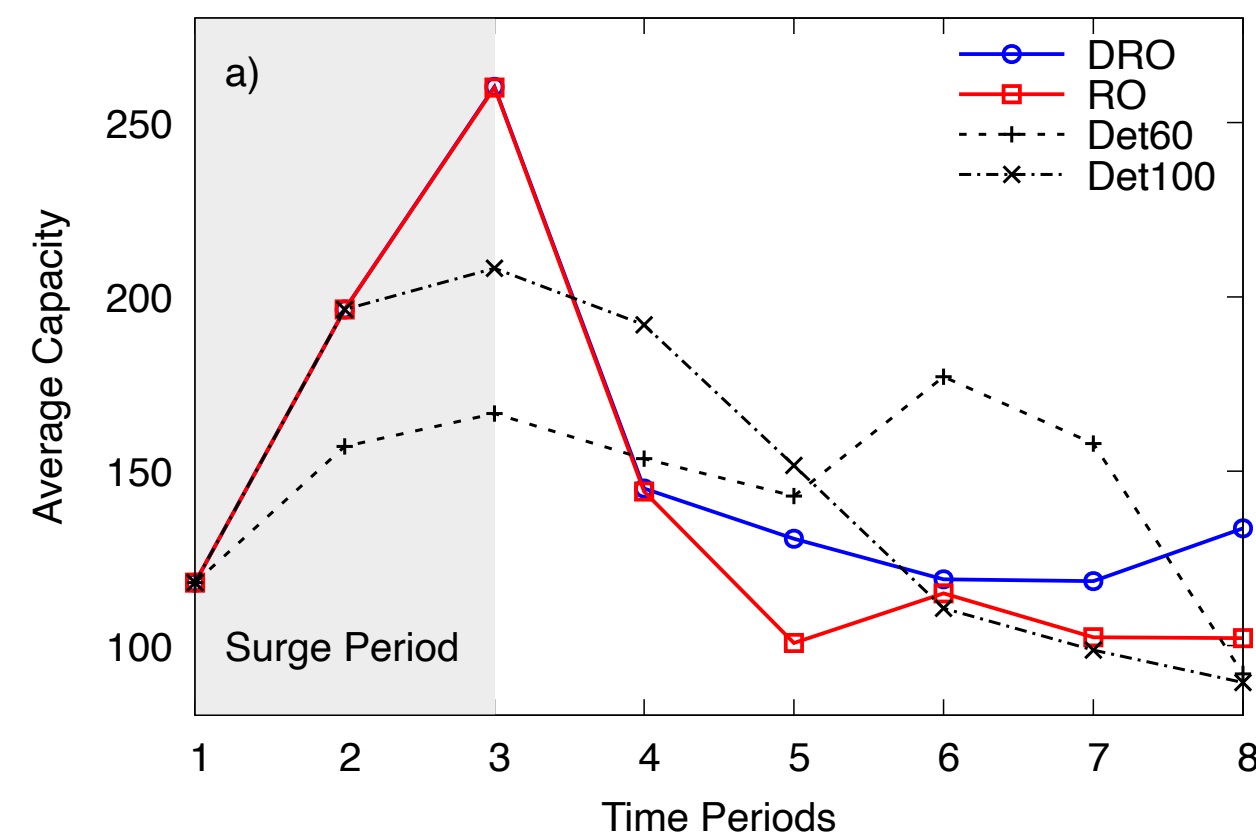


(c) Heatmap of **RO-DRO**

- RO** becomes more preferable than **DRO** when a decision-maker faces both higher expansion and departure costs.

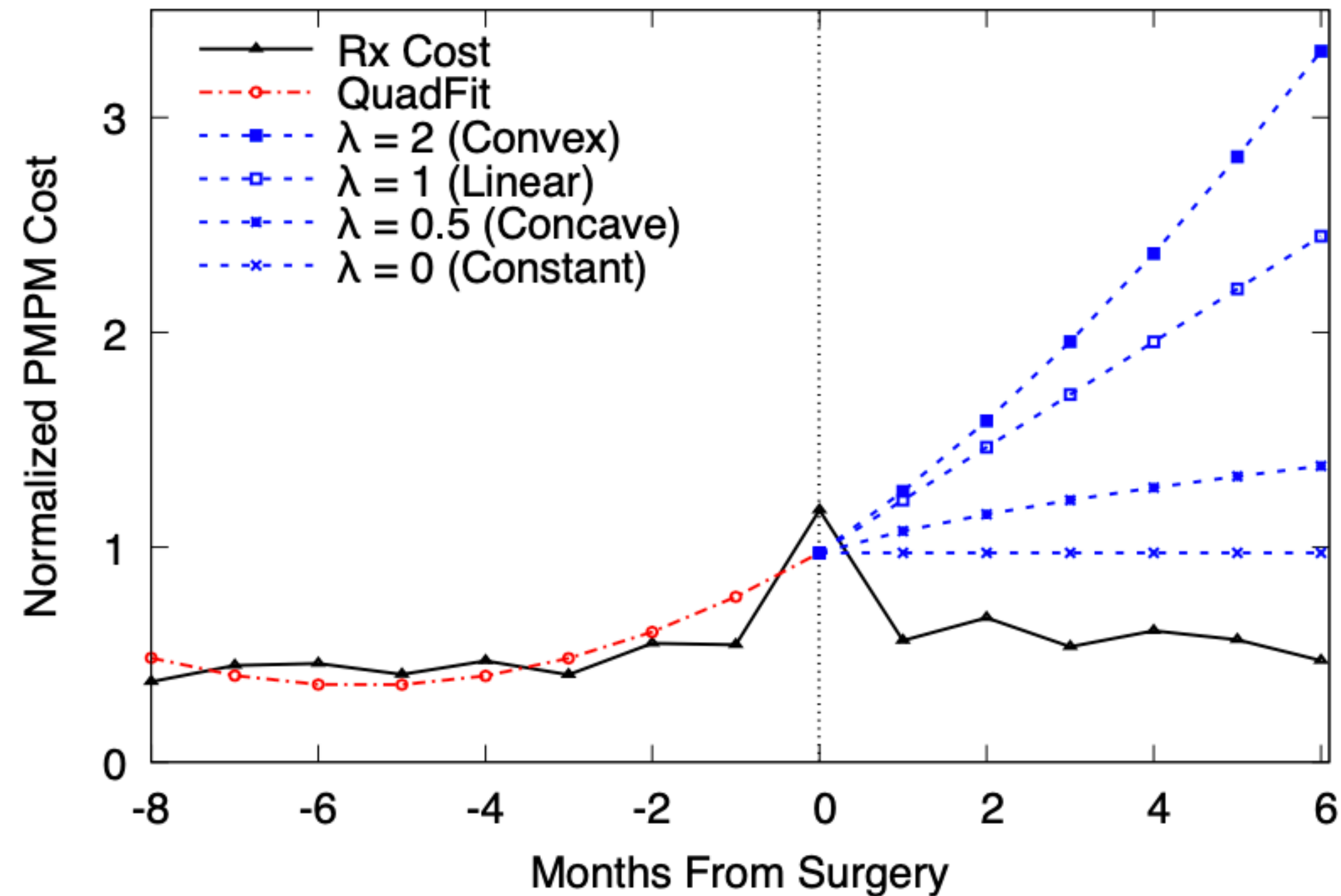
Conclusions

- Dynamic expansion of surgical capacity is necessary to manage a large number of deferred surgeries.
- We develop two optimization methods, based on RO and DRO.
- We introduce the notion of tree of uncertainty products to make RO models tractable.
- Proposed methods significantly improve objectives (5~10%) over deterministic policies in the hernia case study.



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Model of Increasing Treatment Costs



$$p_{t-\tau}(\lambda) = q_2 \cdot (t - \tau + 1)^\lambda + q_1 \cdot (t - \tau + 1)^{\min(\lambda, 1)} + (q_0 - q_1 - q_2).$$

- The cost increases with delay, but the rate of increase depends on the choices.