

Data-driven Distributionally Robust Optimization over Time

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Joint work with Kevin-Martin Aigner, Kristin Braun, Sebastian Pokutta, Frauke Liers, Andreas Barman, Oscar Schneider, and Sebastian Tschupik













 Develop optimization under uncertainty model that incorporates new information as a part of optimization process





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- DRO can integrate new samples while accounting for uncertainty

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 $\mathbb{E}_{s \sim p}\left[f(x,s)\right]$





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- DRO problems are difficult to solve
 - Dualization increases the size of the problem
 - It also removes any special structure

$$\mathbb{E}_{s \sim p}\left[f(x,s)\right]$$



Existing Work





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DRO over Time



Uses recomputation of exact solution with updated ambiguity set (Bayraksan) and Love 2015, Esfahani and Kuhn 2018, Kirschner et. al. 2021 ...)



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Faster Solutions Methods

 Convert DRO problem into a regularisation problem (Namkoong and Duchi 2016, Chen et al 2017, Levy et al 2020 ...)





Contributions

- We provide an Online Algorithm for DRO that simultaneously learns the uncertainty set and converges to the optimal solution
- We prove the consistency of our algorithm and also bound its regret over time
- We illustrate the performance of our method through numerical experiments on benchmark libraries.











Learning

- Observe samples from a distribution p^* (finite dimension)

• Use samples to construct ambiguity set \mathscr{P}_0 containing p^* with high probability





Learning

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Optimization

• Leverage ambiguity set \mathscr{P}_t to make robust decisions x_t

• Use samples to construct ambiguity set \mathscr{P}_0 containing p^* with high probability





Learning

- Observe samples from a distribution p^* (finite dimension)

Optimization

• Leverage ambiguity set \mathscr{P}_t to make robust decisions X_t

Learning

• Use new observations to update the set \mathscr{P}_{t+1} and repeat

• Use samples to construct ambiguity set \mathscr{P}_0 containing p^* with high probability





Confidence Interval Ambiguity Set

$\mathcal{P}_t = \left\{ p \in \mathcal{P}_0 \mid |p - \hat{p}_t| \le \frac{z_{\frac{\delta_t}{2}}}{\sqrt{t}} \right\}$



- Confidence Interval Ambiguity Set
- ℓ_2 -norm Ambiguity Set



$$\mathcal{P}_t = \left\{ p \in \mathcal{P}_0 \mid |p - \hat{p}_t| \le \frac{z_{\frac{\delta_t}{2}}}{\sqrt{t}} \right\}$$
$$\mathcal{P}_t = \left\{ p \in \mathcal{P}_0 \mid ||p - \hat{p}_t||_2 \le \frac{\sqrt{2|\mathcal{S}\log(2/\delta_t)}}{\sqrt{t}} \right\}$$



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- Kernel based Ambiguity Set



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$$\mathcal{P}_t = \left\{ p \in \mathcal{P}_0 \mid ||p - \hat{p}_t||_M \leq \frac{\sqrt{C}}{\sqrt{t}} (2 + \sqrt{2\log(1/\delta_t)}) \right\}$$



- Confidence Interval **Ambiguity Set**
- ℓ_2 -norm Ambiguity Set
- Kernel based **Ambiguity Set**
 - The sets include the true distribution with high probability



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- Confidence Interval Ambiguity Set
- ℓ_2 -norm Ambiguity Set
- Kernel based Ambiguity Set
 - The sets include the true distribution with high probability
 - They shrink fast enough to compensate for the increasing probability requirements



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DRO Problem

$\widehat{J}_t := \min_{x \in \mathcal{X}} \max_{p \in \mathcal{P}_t} \mathbb{E}_{s \sim p} \left[f(x, s) \right]$



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 Dual Reformulation for Interval Ambiguity Sets

 $\min_{x,z,\alpha,\beta} z - \langle l_t, \alpha \rangle + \langle u_t, \beta \rangle$ s.t. $z - \alpha_k + \beta_k \ge f(x, s_k) \quad \forall k = 1, \dots, |\mathcal{S}|,$ $\alpha, \beta \ge 0,$ $x \in \mathcal{X}, \ z \in \mathbb{R}, \ \alpha, \beta \in \mathbb{R}^{|\mathcal{S}|}.$



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Algorithm 1 DRO over Time

- 1: Input: functions $f(\cdot, s)$ for $s \in S$, feasible set \mathcal{X} , initial amb
- 2: **Output**: sequence of DRO solutions x_1, \ldots, x_T
- 3: for t = 1 to T do
- 4: $x_t \leftarrow \text{solve Problem (1) or (2) for } \mathcal{P}_{t-1}$
- 5: $\mathcal{P}_t \leftarrow$ observe data and update set parameters such as f ambiguity set.
- 6: **end for**









• Initial solutions x_0 and p_0

• Step by adversary *p*



- Step by adversary p
- Step by decision maker *x*



- Step by adversary p $p_t = \arg \min_{\sigma \mathcal{D}} p_t$
- Step by decision maker *x*

 $p_{t} = \arg\min_{p \in \mathcal{P}_{t-1}} \left\langle -\eta \nabla_{p} \mathbb{E}_{s \sim p_{t-1}} \left[f(x_{t-1}, s) \right], p \right\rangle + \frac{1}{2} \|p - p_{t-1}\|^{2}.$



- Step by adversary p $p_t = \arg \min_{p \in \mathcal{P}_{t-1}} p_t$
- Step by decision $x_t = \arg \min_{x \in \mathcal{X}} \mathbb{E}_{s \sim p_t}[f(x, s)]$ maker x

$$\sum_{t=1}^{n} \left\langle -\eta \nabla_p \mathbb{E}_{s \sim p_{t-1}} \left[f(x_{t-1}, s) \right], p \right\rangle + \frac{1}{2} \|p - p_{t-1}\|^2.$$

$$\mathbb{E}_{s \sim p_t} [f(x, s)]$$



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- 4: Set $p_0 = \left(\frac{1}{|S|}, ..., \frac{1}{|S|}\right) \in [0, 1]^{|S|}$
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Online Optimization

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- 6: for t = 1 to T do
- $\tilde{p}_t \leftarrow p_{t-1} + \eta \nabla_p \mathbb{E}_{s \sim p_{t-1}} \left[f(x_{t-1}, s) \right]$ 7:
- 8: $p_t \leftarrow \arg\min_{p \in \mathcal{P}_{t-1}} \frac{1}{2} \|p \tilde{p}_t\|^2$



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Online Optimization

Algorithm 2 DRO over Time with Online Projected Gradient Descent

- 1: Input: functions $f(\cdot, s)$ for $s \in S$, feasible set \mathcal{X} , initial ambiguity set \mathcal{P}_0
- 2: **Output:** $x_1, ..., x_T$
- 3: Set $\mathcal{P}_0 = \{ p \in [0, 1]^{|\mathcal{S}|} \mid \sum_{k=1}^{|\mathcal{S}|} p_k = 1 \}$
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- 10:ambiguity set.



 $\mathcal{P}_t \leftarrow \text{observe data and update set parameters such as } \hat{p}_t, l_t, u_t \text{ and } \epsilon_t \text{ as per the type of}$
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11: end for



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Proof technique:

True distribution inside ambiguity set

• The ambiguity set converges to the true distribution





With probability at least $1 - \delta$ we have $\frac{1}{T} \sum_{t=1}^{T} \left(\max_{p \in \mathcal{P}_t} \mathbb{E}_{s \sim p} \left[f(x_t, s) \right] - \min_{x \in \mathcal{X}} \max_{p \in \mathcal{P}_t} \right]$

$$\sup_{t} \mathbb{E}_{s \sim p} \left[f(x, s) \right] \right) \leq G \sqrt{\frac{|\mathcal{S}| h(T)}{2T}} + \frac{2G}{T},$$





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Here

 $h(T) \in \mathcal{O}(|\mathcal{S}|\log^2(T))$





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Here

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• Linear Dependence on Scenarios

$$\sup_{t} \mathbb{E}_{s \sim p} \left[f(x, s) \right] \right) \leq G \sqrt{\frac{|\mathcal{S}| h(T)}{2T}} + \frac{2G}{T},$$









Bound the regret term by the linear drop in the function value

$\sum_{t=1}^{T} \left(\max_{p \in \mathcal{P}_t} \mathbb{E}_{s \sim p} \left[f(x_t, s) \right] - \min_{x \in \mathcal{X}} \mathbb{E}_{s \sim p_t} \left[f(x, s) \right] \right) = \sum_{t=1}^{T} \left\langle \nabla g_t(p_t), p_t - u_t \right\rangle$





Bound the regret term by the linear drop in the function value



gradient and the cumulative length of the steps taken

$$\sum_{t=1}^{T} \langle \eta \nabla g_t(p_t), p_t - u_t \rangle \leq \sum_{t=1}^{T} \frac{\eta^2}{2} \| \nabla g_t(p_t) \|^2 + \sum_{t=1}^{T} \left(\frac{1}{2} \| p_t - u_t \|^2 - \frac{1}{2} \| p_{t+1} - u_t \|^2 \right)$$

$$\mathcal{L}_{p_t}\left[f(x,s)\right]\right) = \sum_{t=1}^T \left\langle \nabla g_t(p_t), p_t - u_t \right\rangle$$

Bound the cumulative linear drop in function value by a bound on the





Bound the regret term by the linear drop in the function value

$$\sum_{t=1}^{T} \left(\max_{p \in \mathcal{P}_t} \mathbb{E}_{s \sim p} \left[f(x_t, s) \right] - \min_{x \in \mathcal{X}} \mathbb{E}_{s \sim p_t} \left[f(x, s) \right] \right) = \sum_{t=1}^{T} \left\langle \nabla g_t(p_t), p_t - u_t \right\rangle$$

- gradient and the cumulative length of the steps taken $\sum_{t=1}^{T} \langle \eta \nabla g_t(p_t), p_t u_t \rangle \leq \sum_{t=1}^{T} \frac{\eta^2}{2} \| \nabla g_t(p_t) \|^2 + \sum_{t=1}^{T} \left(\frac{1}{2} \| p_t u_t \|^2 \frac{1}{2} \| p_t u_t \|^2 \right)$
- size.

$$\sum_{t=1}^{T} \left(\frac{1}{2} \| p_t - u_t \|^2 - \frac{1}{2} \| p_{t+1} - u_t \|^2 \right) \le \sum_{t=1}^{T} \frac{1}{2} \| p_t - u_t \|^2$$

Bound the cumulative linear drop in function value by a bound on the

$$(p_t)\|^2 + \sum_{t=1}^T \left(\frac{1}{2}\|p_t - u_t\|^2 - \frac{1}{2}\|p_{t+1} - u_t\|^2\right)$$

Bound the cumulative length of the steps on the basis of the uncertainty set





• Primarily focuses on the gap between adversarial solutions p_t



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- Uses construction of ambiguity sets to bound the gap on the sequence of generated adversarial solutions



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$$\frac{1}{2} \sum_{t=1}^{T} \|p_t - q_t\|^2 \le h(T)$$

 $p_t \in \mathcal{P}_{t-1}, q_t \in \mathcal{P}_t$



- Primarily focuses on the gap between adversarial solutions p_{t}
- Uses construction of ambiguity sets to bound the gap on the sequence of generated adversarial solutions

$$\begin{split} \frac{1}{2} \sum_{t=1}^{T} \|p_t - q_t\|^2 &\leq h(T) \quad \text{Confidence Intervals} & h(T) = 8|\mathcal{S}|\log(\pi T)(1 + \log T) \\ p_t &\in \mathcal{P}_{t-1}, q_t \in \mathcal{P}_t \quad \mathscr{C}_2\text{-norm Sets} & h(T) = 8|\mathcal{S}|\log\frac{\pi T}{\sqrt{3\delta}}(1 + \log T) \\ \text{Kernel based Sets} & h(T) = \frac{32C}{\lambda^2} + \frac{32C}{\lambda^2}\log\frac{\pi T}{\sqrt{6\delta}}(1 + \log T) \end{split}$$





Numerical Experiments

Benchmark Libraries

- MILPs and MIQPs from the MIPLIB set of benchmark Instances lacksquare
- Comparisons against other methods \bullet

Distributionally Robust Network Design

Network design with uncertain demands. Instances by Altin et. al. (2007)

- ChicagoSketch model from Transportation Networks library
- Illustration of impact on solutions



Benchmark Libraries

- Takes MILP and MIQP instances from MIPLIB library
- Instances are of the form

$$f(x,s) = x^{\mathsf{T}}Qx + (c+s)^{\mathsf{T}}x + d$$



Objective uncertainty in the instances through scenarios $s \in \mathcal{S}$ with $|\mathcal{S}| = (2, 10, 15)$





Benchmark Instances: Different Ambiguity Sets





Benchmark Instances: Different Ambiguity Sets









Benchmark Instances: Different Ambiguity Sets



The objective value shrinks for all set types

Fastest reduction for confidence intervals











	$ \mathcal{S} $	Online Robust	Exact DRO
MIP (I)	10	$52.4\mathrm{s}$	115.8s
MIP (ℓ_2)	10	49.4s	127.5s
MIP (K)	10	56.3s	129.5s
MIP(I)	50	57.7s	176.7s
MIP (ℓ_2)	50	60.4s	206.1s
MIP (K)	50	67.0s	244.4s
MIQP (I)	2	170.2s	271.4s
MIQP (ℓ_2)	2	186.3s	329.5s
MIQP (K)	2	188.6s	359.6s

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More time savings for large and non linear problems









	$MIP \\ \mathcal{S} = 10$	$MIP \\ \mathcal{S} = 50$	
DRO Wassertein DRBO	45.6s 52.3s $42.7s^{**}$	$55.9s^{*}$ 59.1s 66.1s^{**}	2' 2' 7
Online robust Running SO	$\begin{array}{c} 26.8 \mathrm{s} \\ 26.6 \mathrm{s} \end{array}$	$\begin{array}{c} 27.1 \mathrm{s} \\ 26.9 \mathrm{s} \end{array}$	$\frac{1}{1}$

- MIQP $|\mathcal{S}| = 2$
- $71.4s^{*}$
- 99.9s
- $38.3s^*$
- 70.2s72.6s





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Online robust methods are significantly faster





Distributionally Robust Network Design

- demand
- Demand is uncertain. Interval ambiguity sets.
- Instances
 - res8: V = 50, E = 77
 - w1 100: V = 100, E = 207
 - w1_200: V = 200, E = 775

Compute minimum cost network topology and edge capacity to satisfy





	$ \mathcal{S} $	Online robust	Exact 1
res8	10	0.2s	0
res8	50	0.6s	11
w1_100	10	0.3s	32
w1_100	50	1.5s	95
w1_200	10	1.2s	38
w1_200	50	4.7s	1282





- Choose the shortest paths in a street network with uncertain arc times
- Model: ChicagoSketch with 933 nodes and 2950 arcs
- Randomly generated true probability distribution for arcs lengths
- Solving directly eliminates structure






































Optimal Route Choice







Optimal Route Choice



Continuous decrease in objective value but discrete jumps due to changing solution





Conclusions

- Method for optimization under uncertainty which combines learning and **Distributionally Robust Optimization** Iterative algorithm for solution of problem which avoid large formulations and maintains structure Theoretical proofs of convergence and solution quality

- Numerical illustrations for the results Aigner et al. "Data-driven Distributionally Robust Optimization over Time." INFORMS Journal on Optimization (2023).

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