

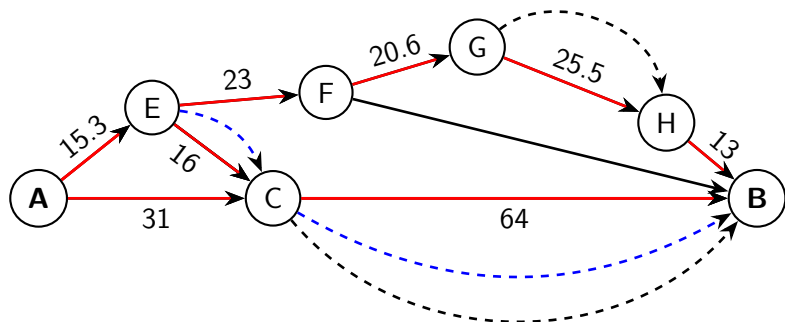
DECISION DEPENDENT UNCERTAINTY WITH UNCERTAIN REDUCTION

Kartikey Sharma and Omid Nohadani

Northwestern University
Industrial Engineering and Management Sciences

October 23, 2019

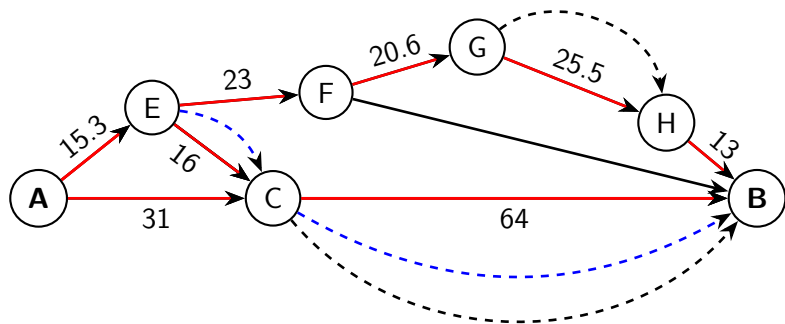
RO WITH DECISION DEPENDENT UNCERTAINTY



$$\Gamma = 1, \gamma = 0.8$$

SP	Nominal = 95	Worst Case = 127
RSP	Nominal = 97.4	Worst Case = 110.15
DDRSP	Nominal = $95.3 + c$	Worst Case = $108.1 + c$

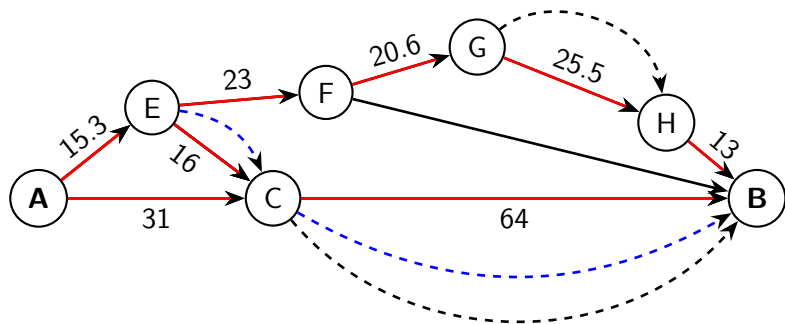
RO WITH DECISION DEPENDENT UNCERTAINTY



$$\Gamma = 1, \gamma = 0.8$$

$$\mathbf{DDRSP \quad Nominal = 95.3 + c \quad Worst Case = 108.1 + c}$$

RO WITH DECISION DEPENDENT UNCERTAINTY



$$\Gamma = 1, \gamma = 0.8$$

DDRSP Nominal = $95.3 + c$ **Worst Case** = $108.1 + c$

If $\gamma = 0.8$ the $c \geq 2.05$ makes reduction not useful which also affects the path chosen.

Other problems leveraging decision dependence

Other problems leveraging decision dependence

- ▶ Facility location problems
 - ▶ The impact of facility on demand may be uncertain

Other problems leveraging decision dependence

- ▶ Facility location problems
 - ▶ The impact of facility on demand may be uncertain
- ▶ Information based interpretation
 - ▶ If the decision being made is the collection of additional information its affect are uncertain by definition

Other problems leveraging decision dependence

- ▶ Facility location problems
 - ▶ The impact of facility on demand may be uncertain
- ▶ Information based interpretation
 - ▶ If the decision being made is the collection of additional information its affect are uncertain by definition
- ▶ Reduction based interpretation
 - ▶ The amount of reduction is uncertain

MATHEMATICAL MODEL

Standard Uncertainty Set

$$\mathcal{U} = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + \Gamma \hat{d}_j] \forall j \in \mathcal{N} \right\}$$

MATHEMATICAL MODEL

Standard Uncertainty Set

$$\mathcal{U} = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + \Gamma \hat{d}_j] \forall j \in \mathcal{N} \right\}$$

Decision Dependent Uncertainty Set

$$\mathcal{U}(\mathbf{y}, \boldsymbol{\gamma}) = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N} \right. \\ \left. d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma_j y_j) \hat{d}_j] \right\}$$

MATHEMATICAL MODEL

Standard Uncertainty Set

$$\mathcal{U} = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + \Gamma \hat{d}_j] \forall j \in \mathcal{N} \right\}$$

Decision Dependent Uncertainty Set

$$\mathcal{U}(\mathbf{y}, \boldsymbol{\gamma}) = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N} \right. \\ \left. d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma_j y_j) \hat{d}_j] \right\}$$

γ_j : reduction parameter

z_j : reduction decision

MATHEMATICAL MODEL

Standard Uncertainty Set

$$\mathcal{U} = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + \Gamma \hat{d}_j] \forall j \in \mathcal{N} \right\}$$

Decision Dependent Uncertainty Set

$$\mathcal{U}(\mathbf{y}, \boldsymbol{\gamma}) = \left\{ \mathbf{d} : \sum_{j \in \mathcal{N}} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N} \right. \\ \left. d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma_j y_j) \hat{d}_j] \right\}$$

How do we choose $\boldsymbol{\gamma}$?

Information about uncertain γ can be described through sets or distributions. For example,

Information about uncertain γ can be described through sets or distributions. For example,

Set based information $\gamma \in G$

- ▶ Interval Sets:

$$G = \{\gamma : \underline{\gamma} \leq \gamma \leq \bar{\gamma}\}$$

Information about uncertain γ can be described through sets or distributions. For example,

Set based information $\gamma \in G$

- ▶ Interval Sets:

$$G = \{\gamma : \underline{\gamma} \leq \gamma \leq \bar{\gamma}\}$$

Distributional uncertainty $\gamma \sim G$

- ▶ Finite distribution:

$$G : P[\gamma = \gamma_s] = \pi_s \quad \forall s = 1, \dots, N_s$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\gamma \in G} \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\gamma \in G} \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- ▶ Leads to expanded uncertainty set $\mathcal{U}(\mathbf{y}) = \bigcup_{\gamma \in G} \mathcal{U}(\mathbf{y}, \gamma)$

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\gamma \in G} \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- Leads to expanded uncertainty set $\mathcal{U}(\mathbf{y}) = \bigcup_{\gamma \in G} \mathcal{U}(\mathbf{y}, \gamma)$

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

$$\mathcal{U}(\mathbf{y}) = \left\{ \mathbf{d} : \sum_{j \in N} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N} \right. \\ \left. d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma_j y_j) \hat{d}_j], \gamma \in G \right\}$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\gamma \in G} \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- ▶ Leads to expanded uncertainty set $\mathcal{U}(\mathbf{y}) = \bigcup_{\gamma \in G} \mathcal{U}(\mathbf{y}, \gamma)$

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

- ▶ Interval case $G = [\underline{\gamma}, \bar{\gamma}]$ leads to point case on the lower bound

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \underline{\gamma})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

SET BASED INFORMATION: ROBUST FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\gamma \in G} \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- ▶ Leads to expanded uncertainty set $\mathcal{U}(\mathbf{y}) = \bigcup_{\gamma \in G} \mathcal{U}(\mathbf{y}, \gamma)$

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

- ▶ Interval case $G = [\underline{\gamma}, \bar{\gamma}]$ leads to point case on the lower bound

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \underline{\gamma})} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right\}$$

- ▶ Solve using an affine policy approach

DISTRIBUTION INFORMATION: STOCHASTIC FORMULATION

DISTRIBUTION INFORMATION: STOCHASTIC FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \mathbb{E}_\gamma \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

DISTRIBUTION INFORMATION: STOCHASTIC FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \mathbb{E}_\gamma \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- Uncertain reduction described set of scenarios of size N_s

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \frac{1}{N_s} \sum_{s=1}^{N_s} \pi_s \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma_s)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

DISTRIBUTION INFORMATION: STOCHASTIC FORMULATION

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \mathbb{E}_\gamma \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- ▶ Uncertain reduction described set of scenarios of size N_s

$$\min_{\mathbf{x} \in X, \mathbf{y} \in Y} \left\{ \mathbf{b}^\top \mathbf{x} + \mathbf{r}^\top \mathbf{y} + \frac{1}{N_s} \sum_{s=1}^{N_s} \pi_s \left[\max_{\mathbf{d} \in \mathcal{U}(\mathbf{y}, \gamma_s)} \min_{\mathbf{z} \in \Omega(\mathbf{x}, \mathbf{d})} \mathbf{c}^\top \mathbf{z} \right] \right\}$$

- ▶ Solve using an affine policy approach
- ▶ Leads to separate policy for each scenario

UNIT COMMITMENT

Day ahead unit commitment with uncertain loads

- ▶ 15 buses
- ▶ $N_g = 9$ generators (index i)
- ▶ $N_d = 11$ loads (index j)
- ▶ $T = 12$ hours (index t)

UNIT COMMITMENT

Day ahead unit commitment with uncertain loads

- ▶ 15 buses
- ▶ $N_g = 9$ generators (index i)
- ▶ $N_d = 11$ loads (index j)
- ▶ $T = 12$ hours (index t)

A new decision is introduced which allows to reduce the maximum possible load for a price.

UNIT COMMITMENT

Day ahead unit commitment with uncertain loads

- ▶ 15 buses
- ▶ $N_g = 9$ generators (index i)
- ▶ $N_d = 11$ loads (index j)
- ▶ $T = 12$ hours (index t)

A new decision is introduced which allows to reduce the maximum possible load for a price.

The amount of maximum load reduced is uncertain.

Load Uncertainty set

$$\mathcal{U}(z, \gamma) = \left\{ \sum_{j \in N} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, \quad d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma z) \hat{d}_j] \right\}$$

Load Uncertainty set

$$\mathcal{U}(z, \gamma) = \left\{ \sum_{j \in N} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, \quad d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma z) \hat{d}_j] \right\}$$

- ▶ Only one reduction parameter γ and decision z

Load Uncertainty set

$$\mathcal{U}(z, \gamma) = \left\{ \sum_{j \in N} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, \quad d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma z) \hat{d}_j] \right\}$$

- ▶ Only one reduction parameter γ and decision z
- ▶ $\Gamma = 2$
- ▶ Price of Reduction = 10/load/time
- ▶ $\hat{d}_j = 10\%$ of \bar{d}_j

Load Uncertainty set

$$\mathcal{U}(z, \gamma) = \left\{ \sum_{j \in N} \frac{|d_j - \bar{d}_j|}{\hat{d}_j} \leq \Gamma \sqrt{N}, \quad d_j \in [\bar{d}_j - \Gamma \hat{d}_j, \bar{d}_j + (\Gamma - \gamma z) \hat{d}_j] \right\}$$

- ▶ Only one reduction parameter γ and decision z
- ▶ $\Gamma = 2$
- ▶ Price of Reduction = 10/load/time
- ▶ $\hat{d}_j = 10\%$ of \bar{d}_j

The unit commitment problem uses the following

- ▶ Unit commitment model from Lorca et al. [1]
- ▶ Decision dependent uncertainty model from Nohadani and Sharma [2]

- ▶ Second stage power generation decisions modeled as affine functions of the realized load given by

$$z_{it} = w_{it} + W_{it} \sum_{j \in N_d} d_{jt}$$

- ▶ Second stage power generation decisions modeled as affine functions of the realized load given by

$$z_{it} = w_{it} + W_{it} \sum_{j \in N_d} d_{jt}$$

- ▶ Constraints involving load are
 1. Demand Satisfaction constraints
 2. Capacity constraints
 3. Ramping constraints
 4. Line flow constraints

PROPOSITION 3 [LORCA ET AL. [1]]

$$\sum_{i \in N_g} w_{it} = 0, \quad \sum_{i \in N_g} W_{it} = 1 \quad \forall t \in T$$

Proposition 3 reformulates the power balance constraints as described above. It can be extended to decision dependent uncertainty sets.

CAPACITY CONSTRAINTS

Capacity constraints are of the following general form

$$c_{it} \sum_{j \in N_d} d_{jt} \leq h_{it} \quad \forall \mathbf{d} \in \mathcal{U}(y)$$

We use the results from Nohadani and Sharma [2] to write the robust problem.

CAPACITY CONSTRAINTS

Capacity constraints are of the following general form

$$c_{it} \sum_{j \in N_d} d_{jt} \leq h_{it} \quad \forall \mathbf{d} \in \mathcal{U}(y)$$

We use the results from Nohadani and Sharma [2] to write the robust problem.

$$\begin{aligned} c_{it} \sum_{j=1}^{N_d} (\bar{d}_{jt} - \Gamma \hat{d}_{jt}) + \max_{\chi, \zeta} \sum_{j=1}^{N_d} ((c_{it} - Mz)\chi_{jt} + c_{it}\zeta_{jt}) \\ \text{s.t.} \quad \sum_{j=1}^{N_d} \frac{|\chi_{jt} + \zeta_{jt} - \Gamma \hat{d}_{jt}|}{\hat{d}_{jt}} \leq \Gamma \sqrt{N_d} \\ 0 \leq \zeta_{jt} \leq 2\Gamma \hat{d}_{jt} - \hat{d}_{jt}\gamma_{jt} \quad \forall j \\ 0 \leq \chi_{jt} \leq \hat{d}_{jt}\gamma_{jt} \quad \forall j \end{aligned}$$

CAPACITY CONSTRAINTS

Capacity constraints are of the following general form

$$c_{it} \sum_{j \in N_d} d_{jt} \leq h_{it} \quad \forall \mathbf{d} \in \mathcal{U}(y)$$

We use the results from Nohadani and Sharma [2] to write the robust problem.

- ▶ z can be either be 0 or 1.
- ▶ c_{it} can be ≥ 0 or < 0 .
- ▶ Leads to 4 possible combinations. The worst case scenarios can be pre-computed the the corresponding cuts generated without iterative cut generation.

RAMPING AND LINE FLOW CONSTRAINTS

In the current model the ramping and line flow constraints are generated using the cut generation algorithm similar to the capacity constraints.

RESULTS

Model	G	Reduced	Obj	Change
--------------	-----	----------------	------------	---------------

RESULTS

Model	G	Reduced	Obj	Change
Nominal			103926.4	
Robust	0		115516.2	11.15%

RESULTS

Model	G	Reduced	Obj	Change
Nominal			103926.4	
Robust	0		115516.2	11.15%
DDU Fixed	0.5	Yes	114557.5	10.23%

RESULTS

Model	G	Reduced	Obj	Change
Nominal			103926.4	
Robust	0		115516.2	11.15%
DDU Fixed	0.5	Yes	114557.5	10.23%
DDU Robust 1	[0.4, 0.6]	Yes	115216.6	10.86%
DDU Robust 2	[0.3, 0.7]	No	115516.2	11.15%

RESULTS

Model	G	Reduced	Obj	Change
Nominal			103926.4	
Robust	0		115516.2	11.15%
DDU Fixed	0.5	Yes	114557.5	10.23%
DDU Robust 1	[0.4, 0.6]	Yes	115216.6	10.86%
DDU Robust 2	[0.3, 0.7]	No	115516.2	11.15%
DDU Stoch. 1	{0.4, 0.5, 0.6}	Yes	114371.3	10.05%
DDU Stoch. 2	{0.3, 0.5, 0.7}	Yes	114083.3	9.77%

CONCLUSIONS

- ▶ Results illustrate how the problem of uncertain reductions can be tackled
- ▶ Using cut generation algorithms and exploiting the structure of uncertainty sets provides scalability for both Robust and Stochastic setting.
- ▶ Our goal in the future is to solve the problem for larger dimensions.

CONCLUSIONS

- ▶ Results illustrate how the problem of uncertain reductions can be tackled
- ▶ Using cut generation algorithms and exploiting the structure of uncertainty sets provides scalability for both Robust and Stochastic setting.
- ▶ Our goal in the future is to solve the problem for larger dimensions.

kartikeysharma2014@u.northwestern.edu

- [1] Álvaro Lorca, X Andy Sun, Eugene Litvinov, and Tongxin Zheng. Multistage adaptive robust optimization for the unit commitment problem. *Operations Research*, 64(1):32–51, 2016.
- [2] Omid Nohadani and Kartikey Sharma. Optimization under decision-dependent uncertainty. *SIAM Journal on Optimization*, 28(2):1773–1795, 2018.